



# Improved Inspection Techniques for Steel Prestressing/Post-tensioning Strand

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## **DISCLAIMER**

The opinions, findings, and conclusions expressed in this publication are those of the authors and not necessarily those of the State of Florida Department of Transportation.

## CONVERSION TABLES

Approximate conversion to SI Units

Symbol	When you know	Multiply by	To find	Symbol
<b>Length</b>				
<b>in</b>	inches	25.4	millimeters	mm
<b>ft</b>	feet	0.305	meters	m
<b>yd</b>	yards	0.914	meters	m
<b>mi</b>	miles	1.61	kilometers	km
<b>Area</b>				
<b>in<sup>2</sup></b>	square inches	645.2	square millimeters	mm <sup>2</sup>
<b>ft<sup>2</sup></b>	square feet	0.093	square meters	m <sup>2</sup>
<b>yd<sup>2</sup></b>	square yard	0.836	square meters	m <sup>2</sup>
<b>ac</b>	acres	0.405	hectares	ha
<b>mi<sup>2</sup></b>	square miles	2.59	square kilometers	km <sup>2</sup>
<b>Volume</b>				
<b>fl oz</b>	fluid ounces	29.57	milliliters	mL
<b>gal</b>	gallons	3.785	liters	L
<b>ft<sup>3</sup></b>	cubic feet	0.028	cubic meters	m <sup>3</sup>
<b>yd<sup>3</sup></b>	cubic yards	0.765	cubic meters	m <sup>3</sup>
<b>Mass</b>				
<b>oz</b>	ounces	28.35	grams	g
<b>lb</b>	pounds	0.454	kilograms	kg
<b>T</b>	short tons (2000 lb)	0.907	megagrams (or "metric ton")	Mg (or "t")
<b>Temperature</b>				
<b>°F</b>	Fahrenheit	5 (F-32)/9 or (F-32)/1.8	Celsius	°C
<b>Illumination</b>				
<b>fc</b>	foot-candles	10.76	lux	lx
<b>fl</b>	foot-Lamberts	3.426	candela/m <sup>2</sup>	cd/m <sup>2</sup>
<b>Force and Pressure or Stress</b>				
<b>lbf</b>	pound force	4.45	newtons	N
<b>lbf/in<sup>2</sup></b>	pound force per square inch	6.89	kilopascals	kPa

# Approximate conversion to US Customary Units

Symbol	When you know	Multiply by	To find	Symbol
<b>Length</b>				
<b>mm</b>	millimeters	0.039	inches	in
<b>m</b>	meters	3.28	feet	ft
<b>m</b>	meters	1.09	yards	yd
<b>km</b>	kilometers	0.621	miles	mi
<b>Area</b>				
<b>mm<sup>2</sup></b>	square millimeters	0.0016	square inches	in <sup>2</sup>
<b>m<sup>2</sup></b>	square meters	10.764	square feet	ft <sup>2</sup>
<b>m<sup>2</sup></b>	square meters	1.195	square yards	yd <sup>2</sup>
<b>ha</b>	hectares	2.47	acres	ac
<b>km<sup>2</sup></b>	square kilometers	0.386	square miles	mi <sup>2</sup>
<b>Volume</b>				
<b>mL</b>	milliliters	0.034	fluid ounces	fl oz
<b>L</b>	liters	0.264	gallons	gal
<b>m<sup>3</sup></b>	cubic meters	35.314	cubic feet	ft <sup>3</sup>
<b>m<sup>3</sup></b>	cubic meters	1.307	cubic yards	yd <sup>3</sup>
<b>Mass</b>				
<b>g</b>	grams	0.035	ounces	oz
<b>kg</b>	kilograms	2.202	pounds	lb
<b>Mg (or "t")</b>	megagrams (or "metric ton")	1.103	short tons (2000 lb)	T
<b>Temperature</b>				
<b>°C</b>	Celsius	1.8C+32	Fahrenheit	°F
<b>Illumination</b>				
<b>lx</b>	lux	0.0929	foot-candles	fc
<b>cd/m<sup>2</sup></b>	candela/m <sup>2</sup>	0.2919	foot-Lamberts	fl
<b>Force and Pressure or Stress</b>				
<b>N</b>	newtons	0.225	pound force	lbf
<b>kPa</b>	kilopascals	0.145	pound force per square inch	lbf/in <sup>2</sup>

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16. Abstract <p>Post-tensioned bridges require a detailed inspection of their post-tensioning systems since damage in these systems is not evident and can result in costly repairs/replacements, loss of integrity and reduction in safety of the bridge. Different nondestructive evaluation (NDE) techniques can be used for the inspection of post-tensioning systems however; there is no systematic way by which a particular NDE technology may be selected for a particular job.</p> <p>This project presents elements and foundation for development of a systematic, job specific approach for the selection of NDE technology for inspection of the post-tensioning systems.</p> <p>In order to achieve this goal, factors affecting the performance of NDE techniques used for the condition assessment of the post-tensioning systems are identified. NDE techniques are then grouped according to their underlying phenomenological bases to put forth the working principles, and pros and cons that can be used for the development of ranking system.</p> <p>It has been found that major difference in grouting practice before and after 2000 affects the selection of NDE technique for the inspection of post-tensioning systems. Other factors affecting the performance of the NDE techniques are the duct system, geometrically difficult zones, and the types of defects. Separate sets of NDE technique are recommended for the internal/external ducts positioned along the traffic and geometrically difficult zones. A job specific "Ranking Index" is proposed for the selection of NDE that takes into account the not only the above mentioned factors but also the cost of conducting NDE. Based on the project findings a roadmap to develop comprehensive methodology to effectively assess the condition of post-tensioned bridge systems is presented.</p>			
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## EXECUTIVE SUMMARY

Post-tensioned structures require a detailed inspection of post-tensioning systems since damage in these systems is not evident and can result in costly repairs/replacements, loss of integrity and reduction in bridge safety. Different damages that require nondestructive Evaluation (NDE) are corrosion of main tension elements, ruptures of post-tensioning tendons, voids in grouted ducts, and damage of corrosion protective barriers. Current challenges of NDE of post-tensioning systems include absence of established framework, lack of proper and safe access, and optimization of level of effort and cost. A nationwide survey conducted as a part of this project indicates that 23 out of 27 states (that participated in survey) have a need for assessment of post-tensioning systems.

This project presents elements and foundation for development of a systematic approach for condition assessment of post-tensioned concrete bridges. The project provides a protocol for condition assessment of steel strands in post-tensioned segmental concrete bridges (Volume II of the report) that is based on investigation of state of the art improved inspection techniques for steel prestressing/post-tensioning strand (Volume I of the report).

NDE technologies that can be used for condition assessment of post-tensioning systems are grouped according to their underlying phenomenological bases. These phenomenological groups of NDE technologies are: Visual methods, Magnetic methods, Mechanical wave/vibration methods, Electromagnetic methods, electrochemical methods, Penetrating radiation methods and other methods. The grouping not only put forth the underlying principles of NDE technologies but also highlights the pros and cons in relation to their application to post-tensioning systems. The pros and cons are discussed and finalized at international workshop arranged by P.I.

Following the discussions at the international workshop, a matrix is established that identifies the merits of various nondestructive testing NDT methods for assessing different conditions. It has been found that a major difference in grouting practice before and after 2000 affects the selection of NDE technique for the inspection of post-tensioning systems. Other factors affecting performance of NDE techniques are duct system (internal or external), geometrical challenges (anchorage zones, deviator, diaphragms, grout presence/absence), and types of defects.

Steps for condition assessment of steel strands in post-tensioned concrete bridges are developed considering the above mentioned factors and are presented in volume II of this report. Separate set of NDE technologies are recommended for the internal/external ducts positioned along the traffic and geometrically difficult zones. NDE technology from each set can be selected based on a job specific “Ranking Index” that is sum of “Efficiency Index” and “Cost Index”. Tables are developed to facilitate the calculation of these indices. Although each NDE technology can have a different “Ranking Index” depending on the job, Magnetic Flux Leakage, Impact Echo, and Impulse Response are identified as promising NDE technologies.

Based on the project findings a roadmap to develop comprehensive methodology to effectively assess the condition of post-tensioned bridge systems is presented.

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# 1 Introduction

Despite all the advantages associated with post-tensioned structures, there have been several concerns about the use of internal and external post-tensioning tendons due to corrosion. Damage related to these events normally is not detected until it is significant and requires costly repairs/replacements. In the meantime, safety and integrity of the bridge remain uncertain. As a result, there is a need for implementing detailed inspections of post-tensioning systems using state-of-the-art condition assessment technologies that utilize nondestructive evaluation (NDE) methods.

***Discussion of Tendon Concerns***—Reports of rust discovered on main tension elements, rusted and ruptured post-tensioning tendons, voids and water-filled voids in grouted ducts, and damage to corrosion protective barriers have created concern. These problems are not limited to the State of Florida and have been found elsewhere here in the U.S. and abroad.

The Florida Department of Transportation has expended significant effort for inspection and rehabilitation of post-tensioning tendons for the Sunshine Skyway Bridge and elsewhere in the state.

***Field Inspection Challenges***—The inspection of post-tensioned bridges provides major challenges for the bridge owner, as post-tensioning elements are not easily accessed. It is impossible to visually assess the condition of the embedded steel elements without using invasive methods, such as drilling a hole and using a borescope. Much of the damage associated with the cables and tendons initiated and propagates hidden from view. Further, local corrosion damage to embedded steel elements does not generally result in visually noticeable changes to the external appearance of the bridge until it is too late. In general, corrosion may result in complete collapse of the bridge without much warning.

There are several other challenges when one attempts to assess the condition of embedded steel elements in post-tensioned bridges. The lack of proper and safe access to tendons adds difficulty to any inspection method. Additionally, these bridges generally have long spans, and the level of effort needed to inspect the entire bridge could be substantial. Therefore one must develop a strategy that can optimize the level of efforts and cost. A single approach may not provide an optimum condition for every case. Having an idea of what needs to be inspected will reduce the level of effort. Conducting certain tests during construction can provide a roadmap on what to inspect during routine inspections. Ideally, the amount of

borescope validation by destructively drilling holes to visually confirm NDE-predicted problems should be reduced.

**Current Practice and Challenges**—Every bridge in state, county and municipal inventories must be inspected at least once every two years. Some require more efforts than others, such as bridges with fracture critical members. Currently there is no established framework to inspect the condition of steel tendons in post-tensioned segmental such that they can be seamlessly connected to condition rating in National Bridge Inspection System (NBIS). It would be desirable to include the condition of embedded steel tendons in post-tensioned bridges as obtained through use of NDE methods, when assigning the condition rating for deck, superstructure and substructure components.

Table 1-1 shows states with more than five segmental concrete bridges, as reported by the American Segmental Bridge Institute (ASBI) report on Durability Survey of Segmental Concrete bridges (September 2007). This table also provides the time span during which these bridges were constructed, last inspection date on the record for all segmental bridges in the inventory and average condition rating for deck, superstructure and substructure components for all segmental bridges in the inventory. As noted in the table, the average conditional rating for most Segmental concrete bridges is relatively good (above 6, except in few cases), yet owners have no way to associate this condition rating to the health of embedded steel tension elements which are integral to safety of the segmental bridges.

**Table 1-1: States with More Than five Segmental Concrete Bridges**

No.	State	Total No.	Construction Time Span	Last Inspection Date	Average Component Conditional Rating Factor (NBI)		
					Deck	Superstructure	Substructure
1	California	9	1974-1996	2006	6.3	7.4	7.0
2	Colorado	18	1977-1993	2006	7.1	6.8	7.0
3	Florida	67	1981-2006	2006	7.5	7.4	7.9
4	Indiana	14	1975-2005	2006	6.4	6.9	7.2
5	Massachusetts	56	1999-2005	2006	7.3	7.0	7.6
6	Mississippi	6	1987-1988	2004	7.8	7.8	7.8
7	New Mexico	10	2002-2004	2004	7.3	7.4	7.4
8	Texas	47	1973-2003	-	6.9	7.4	6.6
9	Washington	5	1981-1996	2004	6.2	5.6	6.2



***On the NDE Methods-*** Following are among the factors that need to be considered when selecting the NDE method for inspecting post-tensioned bridges.

- a) Defect sensitivity,*
- b) Test repeatability and consistency,*
- c) Test time and access requirements,*
- d) Test operator requirements,*
- e) Scale effect (laboratory scale vs. full scale),*
- f) Application cost, and*
- g) Capability to tie the developed information to NBIS conditional rating of deck, superstructure and substructure conditional rating.*

## **1.1 Brief Overview of Post-Tensioning Systems**

According to a report published by the Federal Highway Administration (FHWA), in 1998, the cost of corrosion in highway bridges in the U.S. was estimated to be \$8.3 billion a year (FHWA 2001). The owners of concrete bridges with various steel elements, especially with pre-tensioned or post-tensioned bridges, in the U.S. and abroad face a serious problem. They have the responsibility of ensuring public safety, but have no means to effectively detect corrosion in these bridges. In the U.S., Powers (1999) had reported serious corrosion problems with post-tensioned bridges. Further, corrosion in post-tensioned bridges with as few as five years of service life has been reported. Collapses of major post-tensioned bridges have also been reported in Belgium and England (Pearson-Kirk 2004).

The post-tensioning method, originated in France by Professor Freyssinet, was used in the design and construction of Veudre Bridge in 1908. The first post-tensioned segmental bridge was also built in France over the River Marne in 1939. The use of post-tensioning in construction of bridges increased significantly in Europe in the mid 1950's and 1960's, and the process gained momentum in the U.S. in the 1970's. A collapse of a post-tensioned bridge in 1967 in the U.K. gave an indication of potential problems with post-tensioned bridges (Pearson-Kirk 2004). During the 1980's, problems with post-tensioned bridges in the U.K. were identified at an alarmingly increasing rate. The collapse of a segmental post-tensioned bridge in Wales in 1985 was the most serious case in the U.K. that finally led the U.K. Department of Transport to issue a memorandum prohibiting construction of post-tensioned

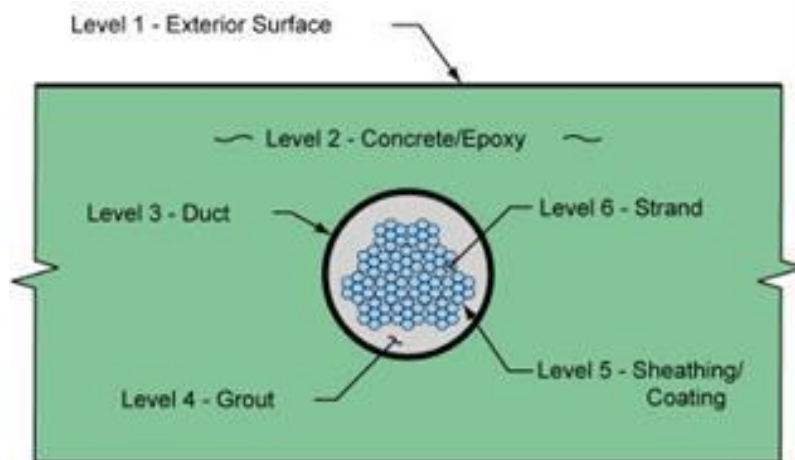
bridges for several years. In 1992, another post-tensioned bridge collapsed in Belgium (the Melle Bridge on the Scheldt River) reinforcing the vulnerability of these structures.

The inspection of most bridges are generally achieved by visual inspection of deck, superstructure and substructure components and assigning condition rating, ranging from zero to nine, with nine indicating excellent condition. Assigning condition rating, in general is very subjective and two inspectors could easily arrive at different conclusions. Within National Bridge Inspection System (NBIS) deck components are generally inspected for cracking, leaching chloride contamination, delamination, excessive wear and sounded for hollow areas. The superstructure inspection depends on type of bridges. The substructure elements include inspection for scour if bridge is crossing waterways.

## **1.2 Observed Field Problems with Post-tensioned Systems**

Early corrosion problems in post-tensioned structures were noticed during 1999 inspection of Niles Channel Bridge, the Mid-Bay Bridge, and the Sunshine Skyway Bridge in Florida (Powers 1999, Beitelman 2000, and DMJM 2003). This led the FHWA to issue a memorandum on January 12, 2001, alerting the State Departments of Transportation of serious corrosion problems with post-tensioned segmental concrete bridges, part of which reads: “... *alert states to the post-tensioned corrosion problems and recommend the expedited inspection of their highest risk post-tensioned structures*”. As a result, several states have taken a lead in comprehending the corrosion challenges in in-service post tension and stay cable systems, and developing advanced technologies. State of Florida leads these efforts.

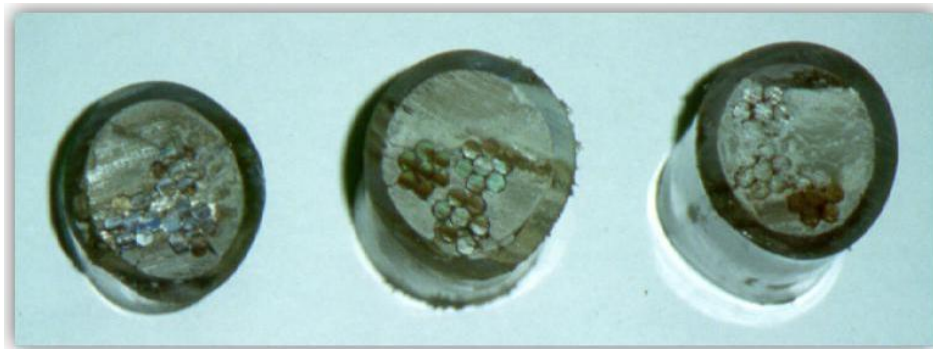
Many of the problems associated with post-tensioned systems can be attributed to grouting which is used to protect corrosion of steel strands inside the duct. Figure 1.1 shows a typical cross section of a duct with steel strands.



**Figure 1.1: Multi-level corrosion protection of steel strands in tendons**

Multi-level protection, as shown in Figure 1.1, helps insure long-term durability of post-tensioned system. In general, the multi-level protection systems for steel strands are: (1) exterior surface, (2) concrete or epoxy cover, (3) duct, (4) grout, (5) strands' sheathing or coating, and (6) strand or bar.

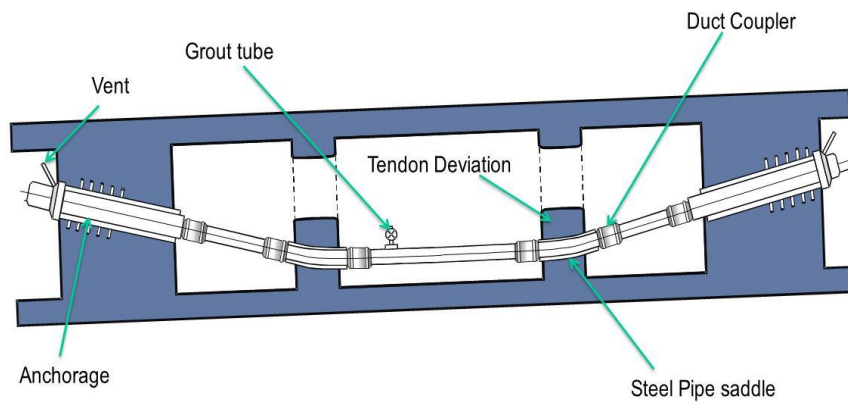
The final arrangement of the strands inside the duct after post-tensioning is not centered, even in straight portion of the tendon. Figure 1.2 shows few examples of cross section of tendons and final arrangement of the steel strands after post-tensioning. To an extent, the flow of grout depends on these final arrangements.



**Figure 1.2: Final arrangement of steel strands inside duct after post-tensioning**

In post-tensioned systems there are two types of tendons, internal and external. The external tendons in segmental systems are used to provide: a) primary tendons in span by span construction, b) supplemental tendons in balanced cantilever bridge construction, c) future tendons, and d) added tendons for repair.

The main elements of external duct system in segmental post tension systems (in span by span construction) are shown in Figure 1.3.



**Figure 1.3: Elements of external ducts in segmental post-tensioning systems**

For longer duct length, splicing is needed. This is achieved using duct coupler. Tendon deviators and anchorage blocks provide reaction for forces created by post-tensioning the strands inside the ducts. Anchorage devices are used for arresting the ends of the strands. Once the strands are post-tensioned, the ducts are grouted using grout tube and vents are used to allow the air to exit preventing formation of voids. Voids provide oxygen and moisture and can result in corrosion of the steel strands. Even though not shown in Figure 1.4, a concrete diaphragm over the pier is present in balanced cantilever construction. Other special details are used in segmental columns. Figure 1.4 shows an example of an external duct in post tension segmental bridge.



**Figure 1.4: External duct**

In many cases the tendons are very close to bottom flange or web surfaces, as noted in Figure 1.4, which provide challenges for inspection.

Major observed problems with external ducts are: a) cracked PE duct, b) grout voids, c) unset, wet, soft, and chalky grout, d) contaminated grout, e) strand corrosion and f) tendon failure.

The existence of void does not necessarily translate to having corrosion at those locations. Figure 1.5(a) and Figure 1.5(b) show examples of strand conditions in the vicinity of voided areas in duct.



(a): Corrosion activity in the voided area



(b): Lack of corrosion activity in the voided area

**Figure 1.5: Corrosion Activity in the Voided Area**

Figure 1.6 shows examples of cracking of the duct. These observed cracking are mainly related to old duct types used and were not created by grouting process. Cracking is mainly attributed to age and durability of the types of materials used. In some cases, corrosion of strands is observed at the vicinities of duct cracking. This is especially true when steel strands are exposed at cracked locations.

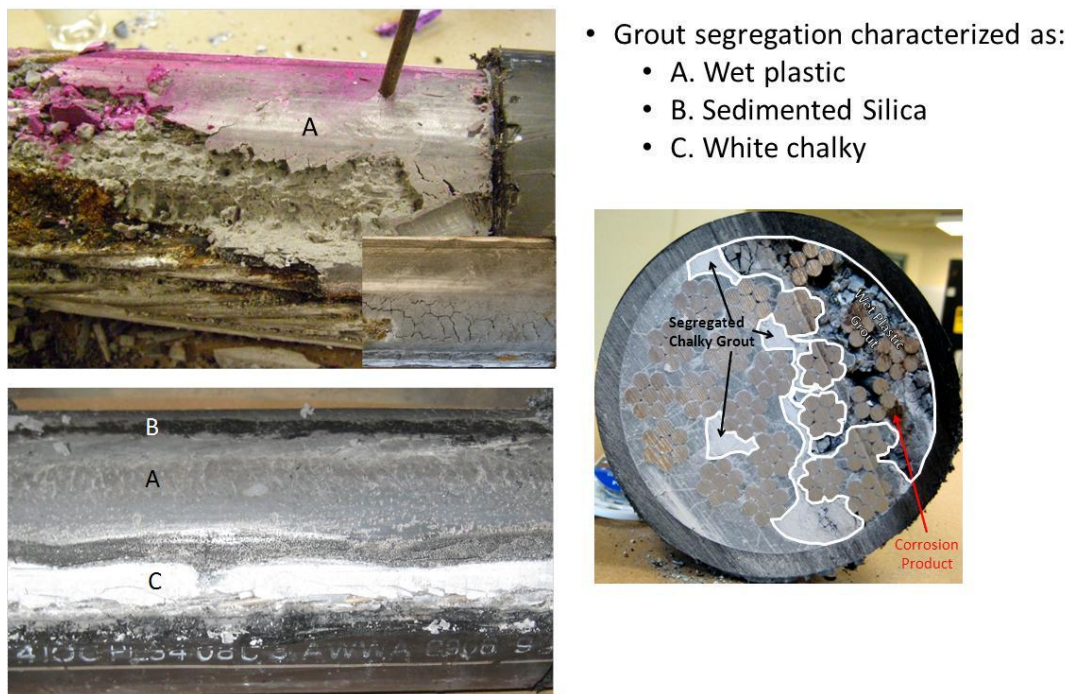


**Figure 1.6: Examples of types of observed cracking of ducts**

Since early 2000, the practice has improved significantly and substantial attention is being paid to training workers, quality of materials used, and documentation of construction. Currently there are number of check and balances in place that significantly reduce the chances of corrosion. Nevertheless,



some of the solutions that were thought to resolve the corrosion problems are creating additional challenges. For instance, grout is used to prevent corrosion of steel strands in post tension concrete bridges. Types of grouts used have gone through significant changes since early 2000. Ducts or stay cables are filled with cementitious material. Most recent grout types used by FDOT are proprietary products. Recently corrosion issues have also surfaced using new proprietary grout types. For instance, Figure 1.7 shows the cross section of a tendon where a new grout type was used. Recent thinking among some practitioners is that most recent corrosion problems observed in the field could be attributed to ingredients used in the grout. More specifically certain characteristics of the grout and grouting practices, which includes a) high chloride content, b) high water demand for new grout types and c) high pressure that is used during grouting process.



**Figure 1.7: Condition of grout ten years after construction (photo courtesy of FDOT)**

The segregation of grout in Figure 1.7 is characterized by having three types of solids, a) region where grout is still wet, even 10 years after construction (wet plastic); b) grout with sedimented silica, which is because of segregation; and c) white chalky grout, which is somewhat hardened, but lacks the characteristics of a superior grout. The grout conditions shown in Figure 1.7 are mainly observed at high points of the tendons. Corrosion of strands is shown to be strongly related to locations where grout was segregated.

## 2 Practices to Assure Durable Post-tensioned Systems

As a result of observed corrosion issues with post-tensioned systems, state DOTs have made significant changes in their practice. Quality of grout, workmanship, and hardware used has improved significantly. Fortunately, the level of redundancies and safety factors used in design are high enough that the observed corrosion issues have not created significant public safety concerns. FDOT implemented new policies and procedures to enhance the long-term durability of their post-tensioned bridges in 2002. These policies and procedures were developed through extensive research highlighted in a ten-volume publication titled “New Directions for Florida Post-Tensioning Bridges” (Corven Engineering, Inc. 2002). The following five strategies have been adopted for providing corrosion protection for post-tensioned bridges: (1) enhanced post-tensioned systems, (2) fully grouted tendons, (3) multi-level anchor protection, (4) watertight bridges, and (5) multiple tendon paths.

One of the major improvements from past practice is the use of plastic duct. Field performance and research has indicated that galvanized metal ducts offer little corrosion protection. Plastic ducts, on the other hand, as shown in Figure 2.1, provide an added layer of protection. Further, plastic ducts are air- and watertight. The quality of grout prior to 2000 was not good. Use of new and proprietary grout types are now the norm with many DOTs.



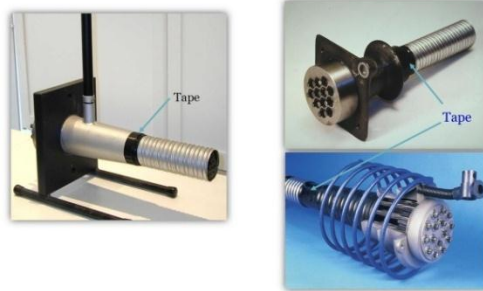
**Figure 2.1: Plastic ducts**

Field observations indicate that one of the major areas of corrosion is at the anchorage areas. As a result newer generations of anchorage systems are being developed, which are believed to resolve corrosion issues in the anchorage areas. Figure 2.2 and Figure 2.3 show the new and old generations of anchorage

devices, respectively. It is worth mentioning that many states no longer permit use of older generation of anchorage devices.

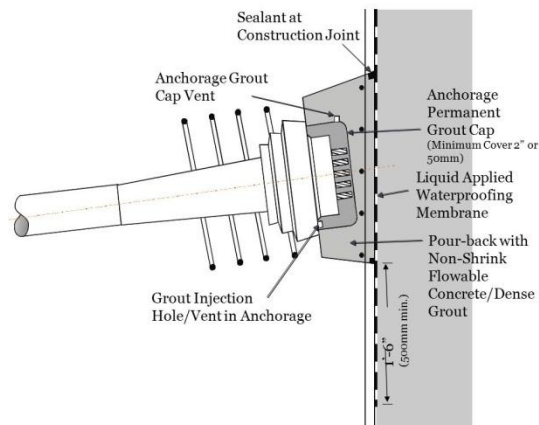


**Figure 2.2: New generation of anchorage devices**



**Figure 2.3: Older generations of anchorage devices; not permitted by some states**

Similar to multiple protection layers for steel strands, recent practices are calling for multiple protection of anchorage regions, as shown in Figure 2.4.



**Figure 2.4: Multiple layer protection system for anchorage regions**

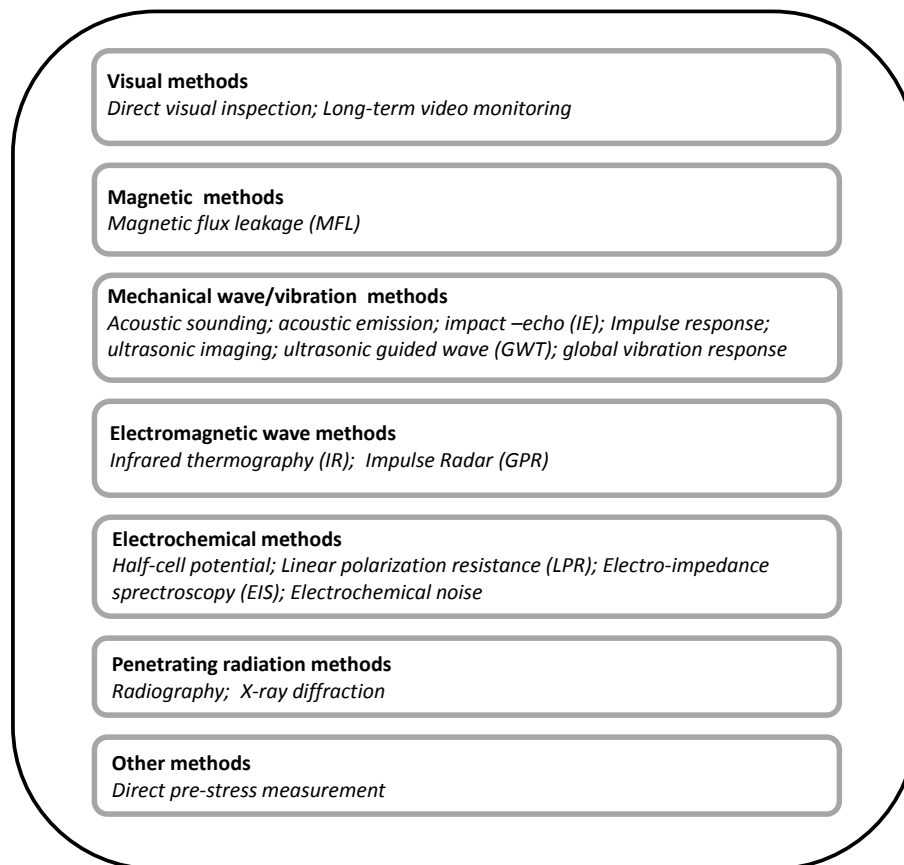


For present practice (in the future, use of ungrouted duct may be a feasibility as it will be easier to inspect and replace strands), the quality of grouting and workmanship is very important. The “Specification for Grouting of Post-Tensioned Structures”, by PTI, provides comprehensive guidelines for grouting. This document is presently undergoing updates. The observed tendon failure at the Niles Channel Bridge, FL in 1999 was attributed the poor grouting practices, inferior design details, and inadequate grout specifications. The key elements for good grouting practices are: a) being able to completely fill the duct, b) low permeability, c) appropriate bleed resistance, and d) careful use of admixtures.

Workmanship and quality control plays a major role in the development of high quality post tension systems. Not too long ago, the grouting was performed by unskilled workers. Starting in early 2000, the practice has changed significantly. It should also be mentioned that research to improve quality of grout used in post tensioned systems are continuing.

### 3 Nondestructive Evaluation Techniques for Post-tensioned and Stay Cable Structures

This section of the report provides a brief overview of meritorious, commonly available and commonly applied nondestructive evaluation (NDE) technologies for condition assessment of post-tensioned and stay cable systems. In this section the NDE technologies are grouped according to their underlying phenomenological bases, as illustrated in Figure 3.1. *More detail and application notes about each of the NDE methods are provided in the Appendix A; there the NDE technologies are grouped according to a specific inspection task goal, such as detection of tendon and cable wire breaks, cross-sectional loss (thinning), or detection of improper grout condition (dry void formation, soft or chalky grout and water intrusion) within tendon or cable ducts.*



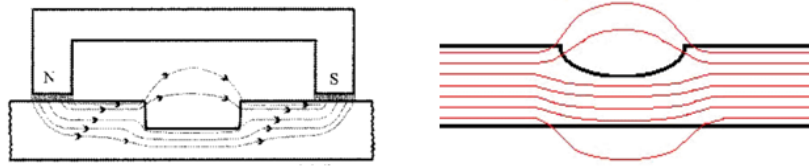
**Figure 3.1: Overview of NDE methods applied to inspect condition of post-tensioned cable systems and cable stays**

### 3.1 Visual Methods

***Direct visual inspection*** is the oldest and the most common form of NDE. It can be used to inspect any structural element and it is employed, in some form, in every inspection effort. By observing the appearance of a component on the exterior, and the interior when possible, an inspector can infer the component's condition. Cracking, fretting, surface corrosion, exfoliation, pitting, and intergranular corrosion can be detected visually when proper access to the inspection area is available. Advancements in technology have extended the capability of visual inspection; devices like fiberscopes, borescopes, magnifying glasses and mirrors, portable and permanent video monitoring equipment, and robotic crawlers aid visual inspection where direct perspective is impractical; for example, the borescope provides enhanced ability to inspect the interior portions of post-tensioned ducts for grout voiding and strand corrosion. Visual inspection is inexpensive and readily applicable, and reliable information about distress and condition is obtained. However, assessment of the condition of interior (hidden from view) elements is not always feasible. Furthermore, borescope technology is time consuming, provides only local information, and requires intrusive drilling.

### 3.2 Magnetic Methods

These methods make use of the interaction between magnetic (and associated electric) fields and their interaction with matter. ***Magnetic flux leakage (MFL)*** is the principal magnetism-based nondestructive testing method that has been applied to inspect distress in ferrous materials, such as that caused by corrosion in strands or bars. It can be used to detect wire strand fracture and thinning in internal or external ducts, as well as stays and ropes. When a magnetic field comes near ferromagnetic (steel) material, the magnetic flux lines will develop within the steel strand. When corrosion disrupts the metal's continuity, this low resistance path becomes blocked and the remaining steel may become magnetically saturated, forcing some of the flux to flow through the air, as illustrated in Figure 3.2. The changes in the vertical components of the flux can be measured by magnetic field (Hall-effect) sensors.



**Figure 3.2: Schematic representation of changes in flux in the location of the corroded area of the strands in active (left) and residual (right) methods**

There are two primary methods for detecting these field anomalies: active and residual. In the active method, the sensors are placed between the poles of the magnet and readings are obtained as the device is passed over the specimen. In the residual system, the specimen is first magnetized; it is important that the strands become magnetically saturated. Then the device is passed over to read the residual magnetic field. Active MFL is appropriate when large areas of corroded regions exist inside the ducts. However, when the corroded area is small, active MFL is no longer effective (Marcel et al. 2009). Both types of MFL are established test methods that can indicate local wire breaks (or member thinning) in near-surface tendons. Furthermore, MFL is a contactless test that does not require connection to tendon, and it works for both metal and plastic ducts. However, the application of MFL for investigating the corrosion of steel strands embedded in concrete presents some challenges: some expertise may be needed to interpret signals, the user may need many magnetizing pre-sessions before signals are reliable; breaks in underlying tendons or in anchorage region cannot be detected readily; the masking effect of the duct; the existence of different layers of reinforcement in the structure that cause disruption to the MFL signal; and limited access to areas, such as the anchorage zone, that are prone to corrosion activities.

### 3.3 Mechanical Wave Propagation and Vibration Methods

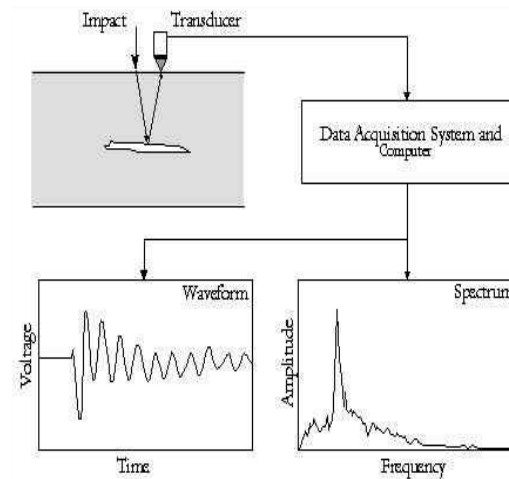
These methods make use of (small amplitude) mechanical motion that is set up in a material. Acoustic, seismic, ultrasonic, and vibrational methods fall into this category. Perhaps the most basic mechanical wave method is *acoustic sounding (also known as hammer tap)*, a simple and common nondestructive testing NDT method applied to different bridge components, including external post-tensioned (PT) ducts and decks. The method is practical, relatively easy to carry out, and fairly accurate in detecting “dry” voids in the grout. In this method, an inspector taps the surface of a structure with a small hammer and then listens to the response. It relies on the experience of the inspector to differentiate the relative sounds generated when the hammer strikes the surface of the tested object: delaminated or voided areas are identified by a dull or hollow sound. Although the sounding method is not expensive, it can be

physically demanding for the inspector and time-consuming. Furthermore, the inspector must be familiar with the tonal differences between undamaged and damaged concrete and be able to distinguish the variations in the tones, so the test is subjective and operator dependent. Areas with high levels of background noise, such as those with large traffic volume or adjacent airports, industry, or construction sites, will make the sound variations difficult to distinguish. Furthermore the method is not able to detect soft grout (unset grout), smaller voids or defects.

**Acoustic Emission (AE)** is a phenomenon of sonic and ultrasonic wave radiation in materials that undergo deformation and fracture processes. For example, corrosion processes induce defects (in service wire fractures) in post-tensioned tendons, which release wave energy that propagates within the tendon and radiates outward. These radiated “acoustic emissions” are detected by surface mounted sensors and the event is detected. When data are acquired by several sensors simultaneously the information is used to locate the defect and, in some cases, provide additional information about the defect. AE is well established technology and field studies have demonstrated the utility of it. Although the basic theory of this technique is simple and well established, its application can be expensive and the process generates large volumes of data that can be difficult to manage and interpret. Furthermore, individual signal may be difficult to interpret or be disrupted by noise, so some expertise is needed; for example in field application it may be difficult to distinguish the emission caused by defects from ambient emissions. Finally, AE cannot detect existing damage; in other words only breaks occurring after the installation of equipment can be detected, so AE sensors must be strategically mounted on structural members.

**Impact-echo (IE)** is a widely used NDT method that has been demonstrated to be effective for detecting defects in concrete structures. IE is a mechanical-wave method based on the transient resonant vibration response of a structure subjected to mechanical impact. The transient time response of the solid structure is measured with a contact sensor (e.g., displacement sensor or accelerometer) mounted on the surface close to the impact source. Recently researchers have developed impact-echo scanning systems, where impact echo data are readily collected over a large area and then presented in an image for effective interpretation. The Fourier transform (amplitude spectrum) of the time-signal will show maxima (peaks) at certain frequencies, which represent particular resonant modes, as illustrated in Figure 3.3. Different types of vibration modes can be set up. The thickness stretch mode normally dominates the spectral response of a plate-like structure that does not contain any near-surface defects, or such structures with a relatively deep defect like a voided post-tension tendon duct. In the former case, the frequency of the fundamental thickness stretch mode can be related to the plate thickness; in the latter case a drop in the

impact-echo resonant frequency mode is associated with the presence of an ungrouted duct that lies underneath the testing point. Impact-echo is a well-established test method, and has been demonstrated to be fairly sensitive to the presence of ungrouted metal tendon ducts; the results for plastic ducts show lower sensitivity though. Also, the signals may be difficult to interpret and some expertise is needed to analyze the data. The conventional test method (contact sensors) can be slow, and difficult to apply in anchorage region or for complicated element geometries.

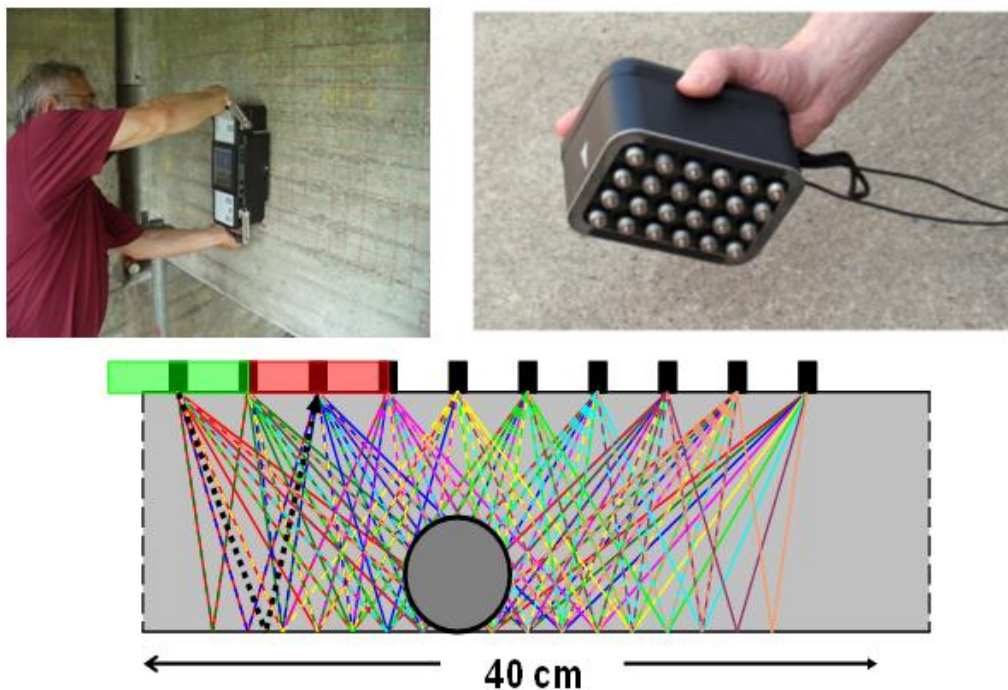


**Figure 3.3: Illustration of impact-echo test method (Sansalone and Streett, 1998)**

The *Impulse Response* test provides a record or signature of the structural (mechanical) vibrational compliance of a structure near a given test location. The testing apparatus consists of a hammer with an attached load cell, capable of generating small force at a point in the deck. The other element of the testing device is a surface-mounted transducer capable of measuring the response of the structure at relatively low frequency ranges; normally a geophone sensor (voltage output proportional to surface velocity) is used. The velocity transducer is placed at every defined testing grid point and an impact event from the instrumented hammer is applied nearby. The loading function data from the hammer and the response signal from the surface sensor are collected and processed. The time signal information is then converted to the frequency domain by using the Fast Fourier Transform (FFT). The resulting velocity spectrum is then divided by the force spectrum to obtain a transfer function, referred to as the “mobility” of the element under the test. Mobility is an index that allows the engineer to quickly assess the local compliance condition, which can be used to illustrate relative changes across the structure. This method has potential to measure mechanical compliance of a structural system, for example an external PT duct which could reflect a duct grouting or other problem, fairly rapidly. However, the signals may

be difficult to interpret and some expertise is needed to analyze the data. Furthermore, the method is relatively insensitive to small defects, or defects located far beneath the tested surface.

Recent advances in ultrasonic array transducer technology have promoted the development of *ultrasonic imaging* capability in concrete. One such development is the shear wave (s-wave) dry point contact transducer array, shown in Figure 3.4; this equipment is commercially available under the MIRA and ICON test equipment packages. Each of the point transducers that are in contact surface and do not require any coupling material between transducer and surface can send and receive an s-wave. As a result, multiple intersecting s-wave paths can be generated across the transducer array set underneath the footprint of the array set. Once the intersecting data set is collected, it is processed using the synthetic aperture focusing technique (SAFT) scheme providing a cross-sectional slice image of the material that is easy, in general, to interpret. A coherent wave reflector represents some inclusion, for example an air void within concrete that is revealed as an indication within the image. The images obtained with commercially available equipment indicate wave reflecting targets, and can be used to identify internal reflectors within concrete, including ducts and even may be applicable to anchorage regions. Recent research on phase changes in reflections shows promise for being able to distinguish further characteristics about the reflector in terms of grouted vs. voided internal PT ducts.



**Figure 3.4: Illustration of ultrasonic s-wave array equipment (top) and data collection scheme (bottom)**

**Ultrasonic guided wave testing** (GWT) utilizes ultrasonic guided waves, which are structure-borne waves that propagate along a structural element, for example propagating along a tendon or stay cable, confined and guided by its geometric boundaries. The propagating waves reflect from any local cross-sectional area change, such as strand breaks or corrosion defects within the tendon itself. The defect location is identified using the arrival time and the velocity of guided wave pulse, and estimates the defect size with the pulse amplitude. GWT uses relatively low-frequency waves (from 5 to 250 kHz) that have a long wavelength with respect to the tendon width in order to have less attenuation for long-range inspection. Magnetostrictive type ultrasonic sensors have been used to apply GWT to free stay cables along their full length. These types of sensors, which are based on the concept that magnetic fields produce small changes in the physical dimensions of a ferromagnetic material (such as steel), are easily applied to free cables: a coil or set of coils that surround the cable sends and receives guided wave pulses along the cable length (Bartels et al. 1998). GWT also offers exciting potential to monitor tendon condition near ends and anchorage zones for wire breaks and grout voids (Mehrabi and Telang, 2003). However, the ends of tendons must be exposed and accessible to apply GWT, and the complicated technology involved can be difficult to apply properly, and the signals are difficult to interpret. Thus testing and analysis expertise are needed.

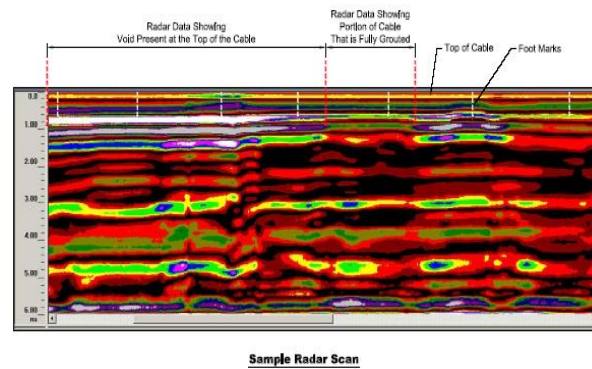
### **3.4 Electromagnetic Wave Propagation Methods**

**The Infrared Thermography (IT)** method has been validated in the laboratory and proven to be economically and technically viable to detect near-surface defects, such as near-surface voiding in grouted PT ducts (Pollack et al. 2008). In this method, variations and disruptions to heat flow are used to detect surface defects on the test object. Both passive (natural heat flow) and active (applied heat) measurements are possible. The method relies on the detection of the variations in the surface temperature profile, which are characterized in an infrared image captured with an infrared camera. IT is a rapid and convenient contactless technique, but it cannot provide meaningful information about internal ducts or other deeper defects.

**Impulse Radar (or ground-penetrating radar, here represented by GPR)** makes use of the interaction of pulsed electromagnetic energy (microwave pulses) with matter. Normally an antenna (or antenna set) is used to emit microwave and then detect any resulting reflections of that emission. GPR is an established method, and test equipment is commercially available; recently 3-D tomographic imaging capability for GPR data has been developed by several manufacturers. It is a contactless method (or nearly contactless in the case of ground coupled antennae) and thus can be rapidly applied. GPR data are



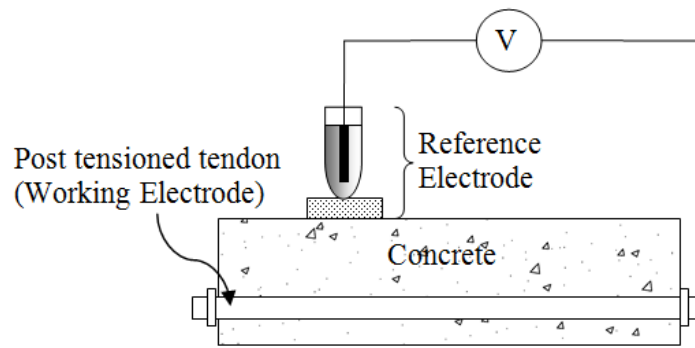
most often presented in the form of a B-scan image, shown in Figure 3.5. GPR is very sensitive to embedded metal, so the method often is used to locate metal ducts in post-tensioned bridges; however, metal ducts completely reflect the radar signal since they are conductive, so that the tendon breaks or grout defects inside the duct cannot be detected. GPR also has potential to monitor grout condition (occurrence of soft, non-setting and chalky grout or cases of water intrusion) within nonconducting (plastic) ducts, as illustrated in Figure 3.5.



**Figure 3.5: Illustration of GPR b-scan image of grouted plastic duct. an occurrence of improper grouting (voiding) is indicated by high reflection levels.**

### 3.5 Electrochemical Methods

Methods that monitor active corrosion normally make use of the electrochemical basis of the process. These approaches offer potential to measure meaningful data related to active corrosion of strand. Most electrochemical techniques use the same measurement set up. It consists of a reference electrode, a working electrode, a counter electrode, and a volt meter as shown in Figure 3.6. Note that a closed electrical circuit is required, so direct electrical connection to the inspected steel must be established. This poses a problem for application to tendons within existing PT ducts with currently available technology because of the requirement that sensors be placed inside the duct. To date, mostly laboratory studies have been conducted so far to check the feasibility of electrochemical techniques for detecting corrosion in post-tensioned strands.



**Figure 3.6: Fundamental measurement setup for electrochemical techniques**

Several different types of electrochemical techniques have been developed. The *half-cell potential* test uses an external half-cell electrode and a voltmeter to detect the voltage differential within the embedded steel reinforcement. The magnitude of the voltage differential has been found to be an indicator of corrosion likelihood. For conventional reinforcing steel in concrete, a voltage potential of less than  $-350\text{mV}$  (assuming a copper-copper sulfate reference electrode) is an indicator of likely corrosion activity. This value is not definitive, and cannot be used to determine the actual corrosion rate. Furthermore, the data are less reliable for prestressing steels, for large concrete covers, and for concrete with certain constituents. *Linear polarization resistance (LPR)* determines the instantaneous corrosion rate in metal. LPR was developed to enable accurate assessment of the condition of the reinforced concrete structures. In LPR, steel is slightly perturbed electrically from its equilibrium potential. This can be accomplished either potentiostatically, by changing the potential by a fixed amount  $\Delta E$  and monitoring the current decay  $\Delta I$  after a fixed time, or galvanostatically, by changing the current by affixed amount  $\Delta I$  and monitoring the potential decay after a fixed time. In both cases, conditions are selected in such a way that potential  $\Delta E$  falls within Stern-Geary range of  $10\text{-}30\text{ mV}$ . LPR measurements have been applied to post-tensioned tendon assemblies and compared to electro-impedance spectroscopy (EIS) tests conducted on the same samples. *Electro-impedance Spectroscopy (EIS)* uses a small amount of alternating current (AC) with a particular frequency applied to a metal-electrolyte interface. Amplitude and phase shift data of the resulting current are measured to calculate the impedance of the interface between concrete and steel. Impedance is a complex number having a real part (resistance) and imaginary part (capacitance). Impedance is calculated for different frequencies of AC. Real and imaginary parts of impedance are plotted for different frequencies and an equivalent circuit can be defined with parameters ( $R_s$ ,  $R_c$  &  $C_{dl}$ ) developed. Values of these parameters are adjusted to best fit the measured data. Finally, the *electrochemical noise* technique monitors fluctuations in open circuit potential and current to infer how the system corrodes. It is mostly used to detect pitting

corrosion. During the initiation and nucleation stages of pitting corrosion, there is a rapid potential drop as electrons accumulate at the metal surface due to the dissolution of metal during a predominantly initial anodic stage. This stage terminates by pit repassivation or some other anodic stage. After repassivation, a predominantly cathodic stage takes place. In the case of tendons, it has the limitation that when current is applied, the surface area of the steel that is being affected cannot be accurately determined and therefore the accuracy of the results is unknown.

### 3.6 Penetrating Radiation Methods

These methods monitor the interaction of high energy electromagnetic radiation, such as x-rays and gamma rays, with matter to draw inferences about that material. **Radiography** involves placement of an x-ray or gamma ray source on one side of the subject structure and a photographic film or digital detector on the backside of the structure. The radiation energy from the source penetrates the subject structure and exposes the film or detector. The amount of x-ray energy that passes through the subject material is related to the line average of mass density along the energy penetration path. A radiograph image is produced, representing a map of density that varies across the material thickness. For example, areas of voiding in ducts show low density; metal tendons show high density, and grout is in between. This graphical output is easy to interpret. This contrast allows for imaging of the conditions of both plastic and metal ducts. Portable linear accelerator x-ray sources used successfully for radiographic inspection of post-tensioning tendons or ducts in concrete have also shown success in detecting wire breaks and voids in stay cable laboratory specimens. X-ray radiography can also be used to image internal concrete conditions including corrosion and void/grout conditions of post-tensioning ducts, and may be applicable to anchorage region with tomographic analyses. However, a primary drawback is radiation exposure hazard to people, and the resulting cost needed to address this issue. Furthermore, it takes more time to apply this method as compared to other NDE methods, and the test geometry and access may be limited as the radiation source and film or digital receiver is on the opposite side. Finally radiographs give no depth of field information unless tomography is used with angled exposures.

**X-ray diffraction** is used to measure stresses in advanced engineering materials such as thin metal lines and interconnects on semiconductor devices, but is rarely applied to civil infrastructure materials. These measurements are used to help solve material failure problems, check quality control, verify computational results, and contribute to fundamental materials research. It precisely determines the distance between planes of atoms in crystalline material through the measurement of peak positions. The positions are then used to determine the elastic strains which can be converted to stresses using

appropriate elastic constants. Plastic deformation can be detected through changes in diffraction peak widths rather than peak shifts.

### **3.7 Other Methods**

*A direct prestress measurement technique* for concrete elements directly measures the available prestress in existing girders and also the available prestress forces in the strands. (Azizinamini et al. 1996). The method is based on an investigation of the state of stress around a hole in a prestressed concrete member. In this method, a cylindrical hole is drilled in the bottom flange of a prestressed girder (assumed to be under compression). The key to application of this method to measure the available prestress in compressed elements is accurate determination of the  $K$  factor, which is very specific to a given geometry.

## **4 Results of Survey**

As part of the project, a survey was conducted to state departments of transportation (DOTs). Objective of the survey was to collect information from different states regarding need for corrosion inspection, major corrosion related problems and challenges, research projects carried out on methodology of corrosion detection, and usage of any non-destructive evaluation tools for inspecting prestressed or post-tensioned strands or stays in bridges.

A total of 27 state DOTs in the survey out of which, 23 had bridges with need for corrosion inspection associated with embedded steel strands or cable stays. Most of the state DOTs reported Bulb-tee or I-beam bridges having a need for corrosion inspection. Ten state DOTs reported to have major corrosion problems and challenges related with the bridges. Detail of these challenges is provided in Appendix B. Seven state DOTs have carried out research projects to develop methodology of corrosion detection and five have previously used nondestructive evaluation tools for inspecting prestressed or post-tensioned strands or stays in bridges.

Appendix B provides a more detail about survey questions and responses by different state departments of transportation.

## **5 Condition Assessment Technologies and Advantages and Disadvantages of Each NDT Method**

A two day long International workshop was held at Florida International University (FIU) with expert participants from Germany, Switzerland, and Australia in addition to the U.S. experts and one researcher from NASA. The workshop was organized and chaired by P.I. One of the objectives of this international workshop was to develop a consensus on advantages and disadvantages of the available NDE technologies; mainly in Civil Engineering field and applicable to condition assessments of post-tensioned and stay cable systems.

As part of the Oct 27 and 28 workshop, significant discussions were carried out and set of conclusions were drawn on advantages and disadvantages of several NDE techniques. Appendix C provides brief summary of outcome from October 27 and 28, 2011 meeting at FIU.

## 6 Matrix for Assessing Effectiveness of Various NDT Methods

There is a need to select most appropriate NDT approach(s) for a given condition. For certain conditions, more than one NDT method may be needed. The objective of this section of the report is to establish a matrix, which identifies the merits of various NDT methods for assessing various conditions.

Conditions that demand use of NDT methods for condition assessment falls into following three general categories:

- a) Post-tensioned concrete bridges constructed prior to early 2000 using old grouting practice
- b) Post-tensioned concrete bridges constructed after observing the corrosion challenges identified in early 2000, using new grouting material.
- c) New post-tensioned concrete bridges which will be constructed in future

There is a fourth category of post-tensioned concrete bridges that are currently under construction. It is assumed that these bridges will be placed under category b with perhaps better conditions.

For each category listed above there are two general post-tensioning duct types:

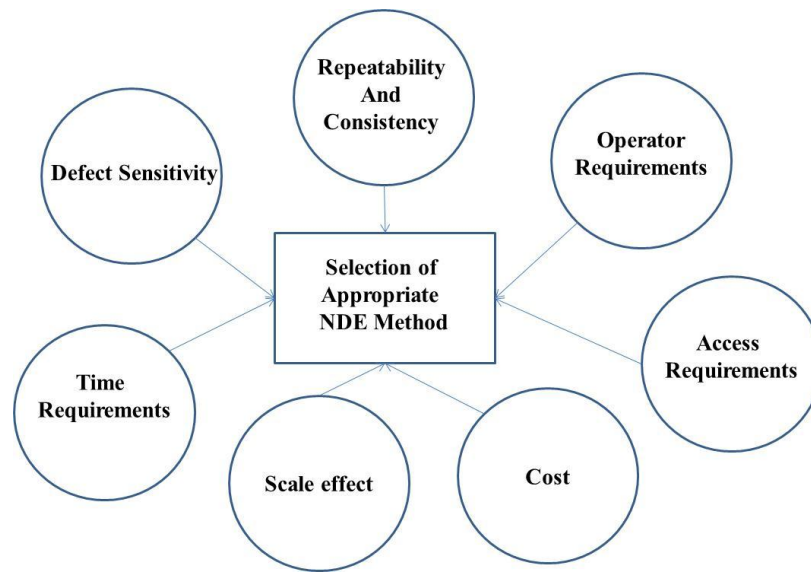
- a) Internal post-tensioned duct systems (both plastic and metal ducts),
- b) External post-tensioned duct systems (plastic ducts),

For each duct type, there are several geometrical factors that dictate the types of NDT methods employable in the field and listed below:

- a) Anchorage zones
- b) Deviators
- c) Diaphragms
- d) Grout type and presence/absence

The choice of NDT method is also influenced by other factors related to each specific method.

Figure 6.1 provides list of factors specific to each NDT method.



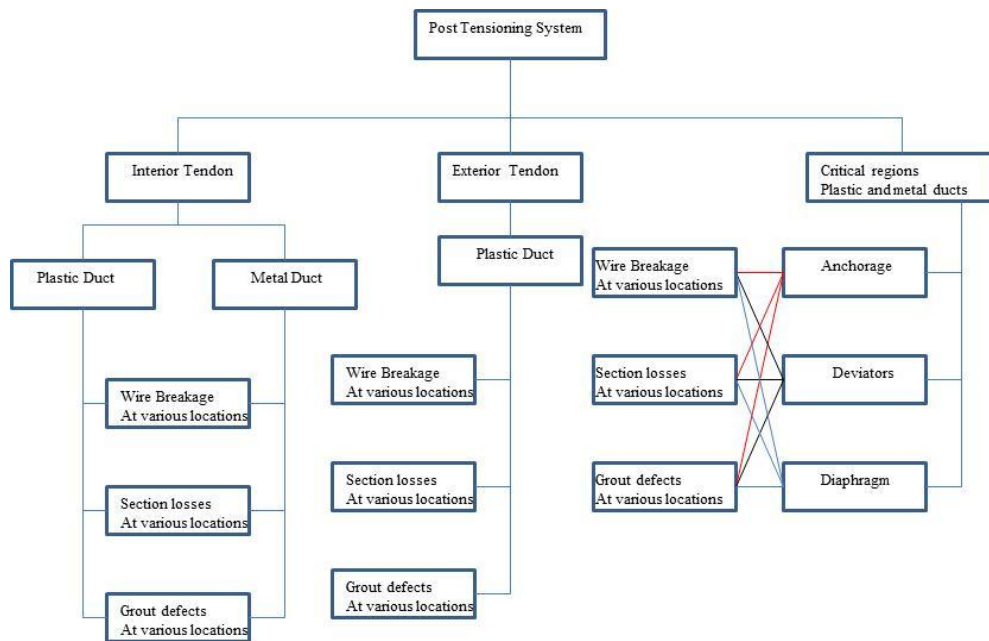
**Figure 6.1: Partial list of factors that influence the selection of most appropriate nde method for a given case**

The selection of appropriate NDT method(s) also depends on types of defects to be identified. Types of defects observed in post-tensioned segmental concrete bridges are:

- a) Wire breakage
- b) Section loss due to corrosion
- c) Voids
- d) Grout defects

Figure 6.2 suggest a nexus of defect types and structural regions and conditions that serves to represent reasonably the range of conditions for post-tensioned systems.





**Figure 6.2: Preliminary list of different conditions and regions of interest for post-tensioned systems**

Considering the discussion presented above, volume II of this project, entitled “FDOT Protocol and Condition Assessment of Steel Strands in Post-tensioned Segmental Concrete bridges” provides steps in health assessment of steel strands.

## 7 Recommendation for Development of a Stand-Alone Guide for Condition Assessment of Post-tensioned Concrete Bridges

FDOT in recent years has carried out a significant amount of research on condition assessment of post-tensioned concrete bridges. Level of knowledge developed by present and past research projects demands development of a comprehensive guide for condition assessment of post-tensioned concrete bridges.

It is recommended to develop a manual titled “Guide for Condition Assessment of Post-tensioned Concrete Bridges” for condition assessment of post-tensioned concrete bridges. This guide can provide detailed instructions, through a set of orderly steps illustrated by examples for the evaluation cases encountered by FDOT. The following could be list of chapters to be included in this guide.

- *Chapter 1—Introduction*—The objective of this chapter will be to introduce the guide, its content, and philosophy. This chapter could provide general description of the guide, general philosophies used for condition assessment, description of main elements involved in condition assessment, and a brief description of contents of each chapter.
- *Chapter 2—Bridge Systems and Post-tensioned element Details*—The objective of this chapter will be to define the types of systems to which the guide is applicable. This chapter would provide a list of various bridge systems for which the guide methodologies for condition assessment could be utilized.
- *Chapter 3—Conditions Needing Inspection*—The objective of this chapter could be to introduce areas of post-tensioning prone to damage. This chapter will provide a comprehensive list of problems needing condition assessment. This chapter will include a list of field-observed problems common to various post-tensioned systems. The guide will be developed such that it could easily be updated as more information and knowledge become available. Case studies will be presented with photos, showing examples of observed field problems.
- *Chapter 4—Available NDE Technologies*—The objective of this chapter could be to introduce various NDE methods and associated information. This chapter could provide

description of various NDE technologies, their advantages, disadvantages, limitations, and any other relevant information with respect to various inspection conditions.

- **Chapter 5—Inspection Selection Strategy**—The objective of this chapter could be to put the various pieces of information together to prescribe an inspection system suitable for a given scenario. The previous chapters will be used to educate the inspectors on different elements of the inspection methodologies to be deployed. This chapter could provide guidelines for selecting one or more appropriate NDE methods along with specific approaches for inspecting a given bridge for a given condition. The conditions to be considered will, at a minimum, contain corrosion, section loss, breakage, grout conditions, voids, water infiltration, and anchorage zones.
- **Chapter 6—Record Keeping**—This chapter will introduce a standard nomenclature for elements, locations, and damage. It will attempt to establish procedures for recording the observations, evaluation of historic data, and developing checklists for NDE method applications and results, and inspection forms comparable to inspection results.
- **Chapter 7—Condition Assessment and Condition rating**—The objective of this chapter could be to translate the NDE and inspection results to a format that is interpretable for condition assessment and condition rating purposes.
- **Chapter 8—Development of Maintenance Plan**—The objective of this chapter will be to develop level of severity, based on the information obtained through condition assessment and produce maintenance plan, which should include plans for post retrofit and rehabilitation. This chapter could also use life cycle cost analysis to conduct cost benefit analysis of various risk level and select an optimum plan.
- **Chapter 9—Case Studies**—A project with relevant work and application will be sought to be included in the guide, as an illustrative example that can be followed by inspectors. This chapter could include tools that could facilitate use of guide for in-service inspection of post-tensioning systems. An example of this type of tool is SAULT (<http://138.47.78.37/sault/home.asp>), which is a Web-based tool developed by Strategic

Highway Research Program 2 (SHRP2) renewal program for locating various classes of utilities.

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# **Appendix A: Nondestructive Evaluation Techniques for Post-tensioned and Stay Cable Structures**



This appendix provides brief summaries of meritorious, commonly available and commonly applied nondestructive evaluation (NDE) technologies for condition assessment of post-tensioned systems. In this section, the visual methods are described first. Next other NDE technologies are presented, categorized by the following inspection task goals:

- a. Detection of tendon and cable wire breaks or cross-sectional loss (thinning)
- b. Detection of improper grout condition (dry void formation, soft or chalky grout and water intrusion) within tendons
- c. Detection of active corrosion of tendons
- d. Characterization of duct position or condition

The following sections provide a brief description of NDE technologies with application to condition assessment of steel strands in post-tensioned systems.

## **A.1 Visual Methods**

Visual inspection is the oldest and the most common form of NDE. It can be used to inspect any structural element and it is employed, in some form, in every inspection effort. By observing the appearance of a component on the exterior, and the interior when possible, an inspector can infer the component's condition. Cracking, fretting, surface corrosion, exfoliation, pitting, and inter-granular corrosion can be detected visually when proper access to the inspection area is available. Latest advancements in technology have extended the capability of visual inspection; devices like fiberscopes, borescopes, magnifying glasses and mirrors, portable and permanent video monitoring equipment, and robotic crawlers aid visual inspection where direct perspective is impractical. For example, the borescope provides enhanced ability to inspect the interior portions of post-tensioned ducts for grout voiding and strand corrosion. Figure A.1 shows images of the interior of a post-tensioned duct obtained using a borescope.

Long term video monitoring enables enhanced characterization of bridge stay cables. Video monitoring is widely used to observe cable sag and to monitor cable motion during extreme wind and rain events. Experience from several investigations on health and integrity of cable-stayed bridges, findings from performance testing, and familiarity with advance nondestructive testing methods have helped in the development of a unified approach for stay cable evaluation (Mehrabi and Ciolko, 2001).

In some cases, visual inspection of stay cables includes hands-on detailed study, which includes the removal of anchorage caps and visual inspection (with and w/o visual aid) of strand ends, sockets, and locking plates, and visual inspection of cable free length. The process has been used to verify the presence of water in and around anchorages and the severity of corrosion activity. It has also identified locations along the cable free length where the extent of deterioration has made significant damage to the corrosion protection barriers. The effectiveness of this method is limited to visible and accessible areas. For visual inspection of fillers and steel wires/strands, and material sampling and testing along the cable free length, cable dissection has also been performed on several bridges (Mehrabi and Telang, 2003). These detailed visual techniques are illustrated in Figure A.2. Table A-1 summarizes the inherent characteristics and applications of visual inspection methods.

**Table A-1: Summary of Inherent Characteristics and Applications of Visual Inspection**

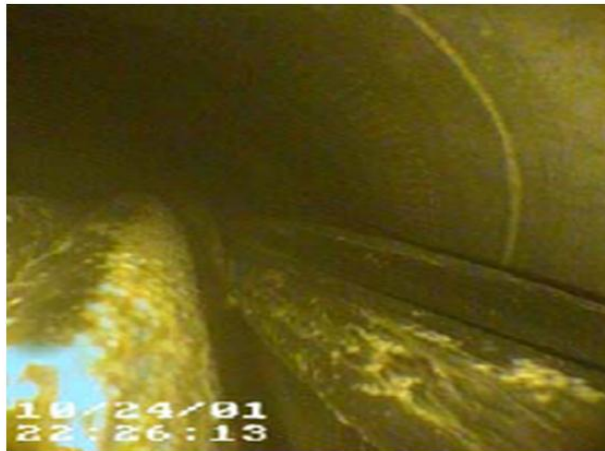
<b>Advantages</b>	<b>Disadvantages</b>	<b>Best application case</b>	<b>Application with regard to duct type</b>
<ul style="list-style-type: none"> <li>• Inexpensive method that is readily applicable.</li> <li>• Reliable information about distress and condition is obtained.</li> </ul>	<ul style="list-style-type: none"> <li>• Cannot assess condition of interior (hidden from view) elements easily.</li> <li>• Borescope technology is time consuming and provides local information, and requires intrusive drilling.</li> </ul>	<ul style="list-style-type: none"> <li>• Inspection of interior of post-tensioned ducts to assess corrosion or voiding condition at one particular location, using borescope.</li> </ul>	<ul style="list-style-type: none"> <li>• Applicable in all inspection cases, but most effective for external ducts, both metal and plastic.</li> </ul>



Partially grouted duct



Partially grouted duct with partially exposed strands



Voided duct with fully exposed strands



Partially grouted duct but no strand exposure

**Figure A.1: Photos of the inside of post-tensioned duct taken by borescopes (DMJM Harris, 2003)**



**Figure A.2: Examples of hands-on inspection of cable with a traveling buggy (left) and a dissected cable, revealing exposed steel cable wires (right)**

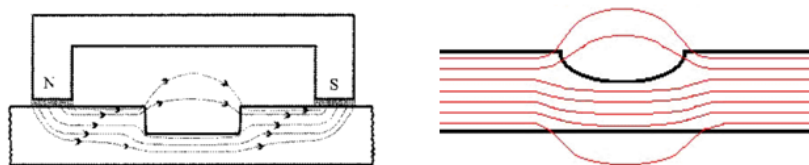
## A.2 Methods to Detect Tendon and Cable Wire Breaks and Cross-sectional Loss

Several NDT technologies have been developed to monitor tendon and wire condition with respect to strand fracture or tendon thinning (loss of metal cross-section). The most prominent methods are summarized below.

### A.2.1 Magnetic Flux Leakage (MFL)

Magnetic flux leakage (MFL) is a nondestructive testing method to inspect ferrous materials to detect distress caused by corrosion in strands or bars. It can be used to detect fiber fracture and thinning in internal or external ducts, as well as stays and ropes. MFL is believed to be a promising nondestructive technique, despite some shortcomings that could be improved.

When a magnetic field comes near ferromagnetic (steel) material, the magnetic flux lines will pass through the steel bar. The steel offers a path of least resistance due to its high permeability, compared to the surrounding air or concrete. When corrosion disrupts the metal's continuity, this low resistance path becomes blocked and the remaining steel may become magnetically saturated, forcing some of the flux to flow through the air. Figure A.3 shows the schematic of this case. The changes in the vertical components of the flux can be measured by magnetic field (Hall-effect) sensors. In fact, total saturation is not required for detection, as orientation of the magnetic field can be altered by even small levels of corrosion.



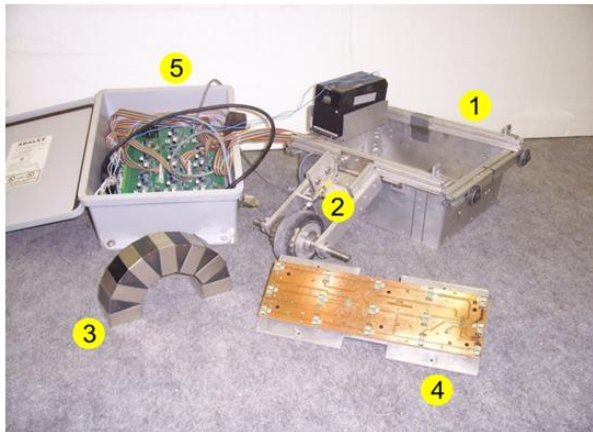
**Figure A.3: Schematic representation of changes in flux in the location of the corroded area of the strands in the active (left) and residual (right) methods (DaSilva, et al. 2009)**

There are two primary methods for detecting these field anomalies: active and residual. In the active method, the sensors are placed between the poles of the magnet and readings are obtained as the device is passed over the specimen. Figure A.3 (left side) illustrates this method. Because the amount of the flux in the ferrous materials depends on the magnetic field surrounding the materials, the location of the magnet and the magnitude of the field are the main variables that affect the collected signal data. The

signals obtained from Hall-effect sensors are affected by many variables, such as the distance between the ducts, concrete cover, type of the duct used (steel versus plastic), number of strands in the duct, level of corrosion, transverse reinforcement in the vicinity of corroded area, level of tension force in the steel strands, and the altitude of the corrosion point. The interaction among these parameters is complex and adds to the difficulty of interpreting the obtained signals.

In the residual system, the specimen is first magnetized and then the device is passed over to read the residual magnetic field. Active MFL is appropriate when large areas of corroded regions exist inside the ducts. However, when the corroded area is small, active MFL is no longer effective. The residual MFL method is mainly aimed to detect smaller areas of corrosion. The detection of a corroded area is done in two stages. First, all strands and bars are magnetized by a magnet, and then the device is passed over the concrete surface to measure the magnetic flux. It is very important that the strands become magnetically saturated. If the object being inspected is not close to saturation, magnetic field will not leak from the defects and the flux lines will instead be able to travel within the surrounding metal. Magnetic saturation of the strands forces the flux lines to enter the air above the defect, allowing the leakage fields to be detected.

The laboratory environment enables isolation of the many influences that affect MFL under field conditions. A simple experiment is used to demonstrate the type of data that could be obtained in the laboratory environment using MFL method. Figure A.4 shows the components of a MFL device constructed by the principal investigator to inspect post tension concrete bridges, and the laboratory setup used.



(a) Device Components



(b) Laboratory Setup

**Figure A.4: MFL equipment developed by the Atorod Azizinamini, P.I. of the proposed project**

The major components of a typical MFL device shown in Figure A.4 are:

- 1) Aluminum housing (as aluminum doesn't affect magnetic field)
- 2) Position indicator (proximity sensor to identify spatial position)
- 3) Magnetic yoke consisting of rectangular blocks of neodymium magnets alternating with wedges of highly permeable, high saturation, magnet iron
- 4) Array of Hall-effect sensors to measure the magnitude of the vertical component of magnetic flux (placed upside down to show sensors); and
- 5) Sensor electronics and signal conditioning board

In the experiment, 19 strands are placed inside a corrugated and galvanized pipe as shown in Figure A.5.

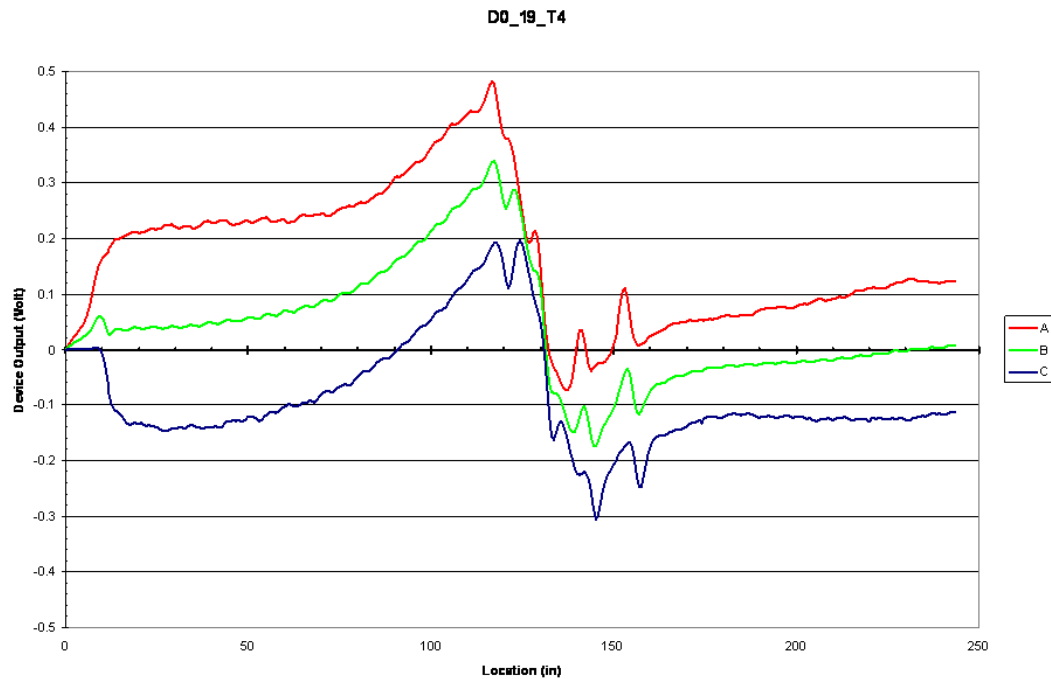




**Figure A.5: MFL test setup used by Atorod Azizinamini**

The MFL equipment is scanned along the horizontal axis of the duct. The total length of the duct is approximately 250 inches. The steel strand extends through the entire length of the duct.

Figure A.6 shows the test results for the condition where all 19 strands are broken in the middle. The vertical axis shows the MFL device output, in terms of voltage, which is related to flux densities. The shape of the curve at the two ends of the duct (zero and 250 inch) is due to end effects. Strand fracture was modeled by physically making a cut in the middle of the strands and allowing each strand to have a small gap in the middle of the duct. The results in Figure A.6 demonstrate that, under ideal conditions, MFL method can locate the damaged areas even in the presence of other reinforcement types.



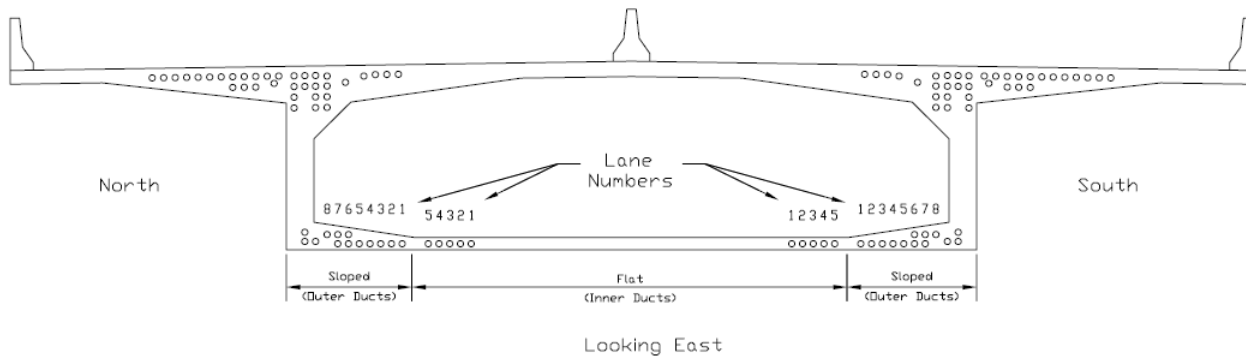
**Figure A.6: MFL test results from laboratory sample showing the effect of 19-strand breakage (large event) and 4 transverse rebars (small ripples) along a concrete element**

In the field, the application of MFL for investigating the corrosion of steel strands embedded in concrete presents the following challenges: the masking effect of the duct; the existence of different layers of reinforcement in the structure that cause disruption to the MFL signal; and limited access to areas, such as the anchorage zone, that are prone to corrosion activities. For instance, Figure A.7 shows a segmental post-tensioned concrete bridge inspected by the P.I., having a number of post-tensioning ducts in top and bottom flanges and a single row in the webs.





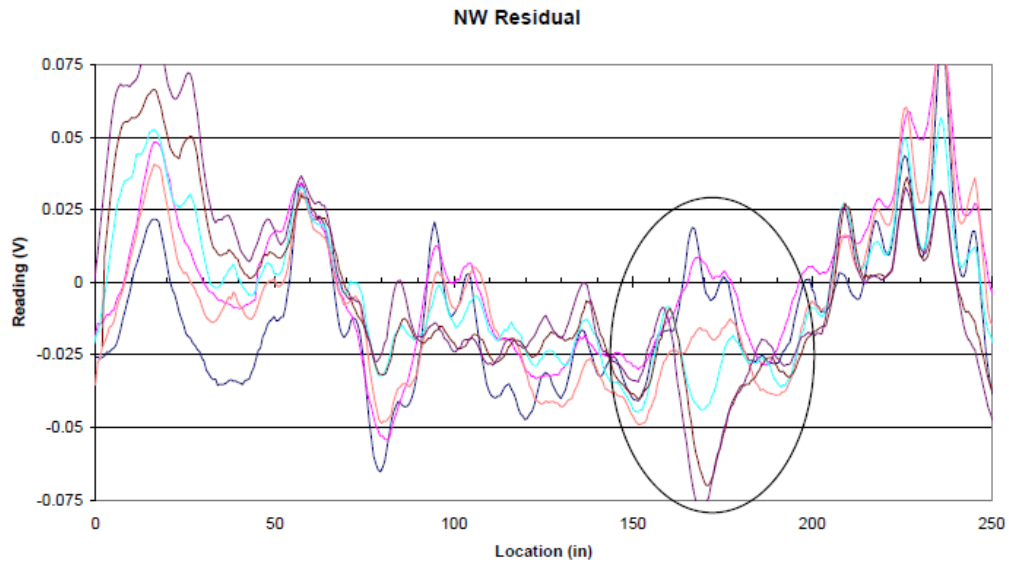
**Figure A.7: An example of major segmental post-tensioned bridge inspected by P.I.**



**Figure A.8: Typical cross section of the bridge**

The figure also shows an MFL signal for several ducts in bottom flange of the bridge. This signal is more complicated than that obtained in the laboratory shown in Figure A.6. The different curves represent different ducts across the section width in the bottom flange. Studying the differences among the curves is an effective strategy for identifying the problem areas. The results are shown in Figure A.9. For instance, the circled region in the figure indicates one duct that is different from the other ducts. Such evidence could be used to conduct more detailed investigation of the subject area, including visual inspection. As will be discussed in later sections, an overall strategy could be to use a hybrid approach, where several nondestructive methods are used to make the final conclusions.

Another approach for effective use of MFL method is to collect the signals every two years or so and look for changes over time. Ideally, the signals would not change with time. Therefore, changes in signal levels over time could be an indication of corrosion activities. In this case, variation in MFL signature will most likely be related to corrosion activity.



**Figure A.9: MFL signals obtained from post-tensioned segmental bridge structure (circle indicates the location of tendon fracture)**

Table A-2 summarizes the inherent characteristics and applications of MFL method.

**Table A-2: Summary of Inherent Characteristics and Application of MFL Method**

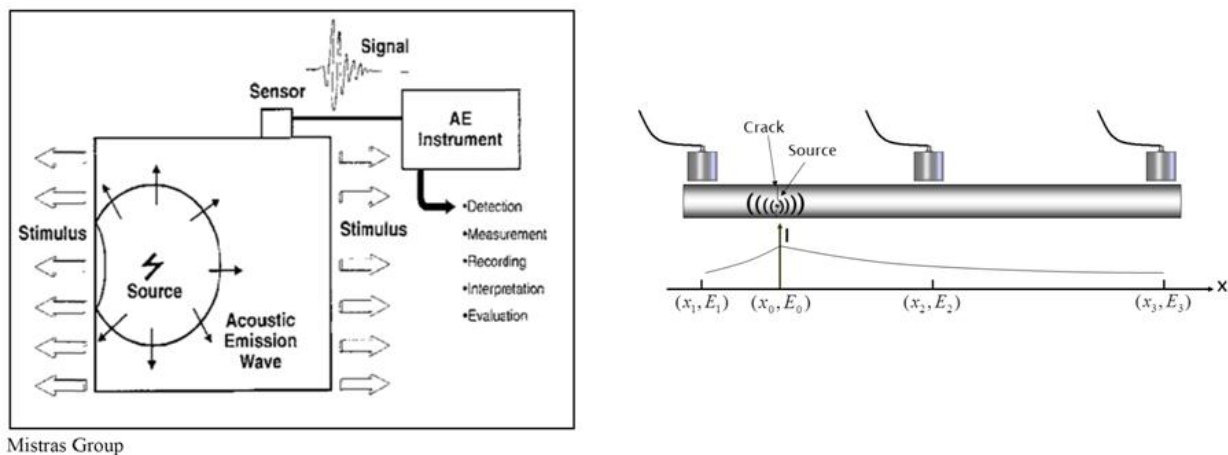
<b>Advantages</b>	<b>Disadvantages</b>	<b>Best application case</b>	<b>What improvement can be made</b>	<b>Application with regard to duct type</b>
<ul style="list-style-type: none"> <li>• Can indicate local wire breaks (or member thinning) in near-surface tendons.</li> <li>• Established test method.</li> <li>• A contactless test that does not require connection to tendon.</li> <li>• Works for both metal and plastic ducts.</li> </ul>	<ul style="list-style-type: none"> <li>• Some expertise may be needed to interpret signals.</li> <li>• May need many magnetizing pre-sessions before signals are reliable.</li> <li>• Cannot detect break in underlying tendons, or in anchorage region.</li> </ul>	<ul style="list-style-type: none"> <li>• Identifying wire breaks in external, plastic ducts.</li> </ul>	<ul style="list-style-type: none"> <li>• Improved performance for congested steel sections and within anchorage region.</li> </ul>	<ul style="list-style-type: none"> <li>• Applicable to both internal and external ducts.</li> </ul>

**A.2.2 Acoustic Emission (AE)**

Acoustic Emission is a phenomenon of sonic and ultrasonic wave radiation in materials that undergo deformation and fracture processes. Corrosion processes induce defects (in service wire fractures) in post-tensioned tendons, which generate acoustic emissions. These emissions are detected by surface mounted sensors. Data acquired by different sensors are used to locate the defect. Although the theory of this technique is simple and well established, the main problem in field application is to distinguish the emission caused by defects from ambient emissions. Only breaks occurring after the installation of equipment can be detected. Vibration sensors are strategically mounted on structural members. These vibration sensors are monitored to “listen” for fracture events due to corrosion of wire strands in the

tendons. With multiple sensors, the locations of such events can be detected through triangulation, as illustrated in Figure A.9.

Recent laboratory research show promising results in detecting the onset of corrosion of bonded prestressing tendons. The researchers found that the expansion around steel at the onset of corrosion caused stress events in the concrete that were detectable. The continuing challenge is to be able to identify these small events in a bridge structure with many other sources of stress events. The researchers concluded that AE could identify the source of corrosion (at least in the small specimens), and the cumulative signal strength of AE was a good indicator of the initiation, propagation, and development of corrosion.

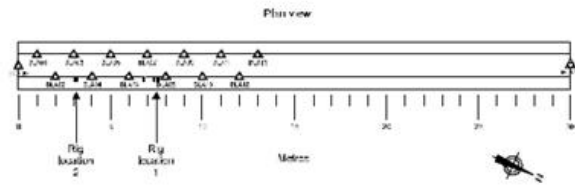


**Figure A.10: Acoustic emission: illustration of fundamental concept (left) and source location with multiple sensors (right)**

Field studies also demonstrate the utility of acoustic emission. In one such study, SoundPrint® equipment was installed on a 30m-long Bank Lane Unit. A post-tensioned footbridge span was recovered from a site to carry out the tests. A simple symmetric array of sensors was used in this case, as shown in Figure A.10.



Instrumented Bank Lane Unit



Sensor installation details

**Figure A.11: Acoustic emission field tests: installation of equipment on bank lane unit (left) and sensor (right) (Cullington et al. 2001)**

Results for the field tests revealed that of the 25 total external wire break events (of which 3 were blind), SoundPrint® analysis of 22 events was rated “excellent” and the remaining 3 events were rated “very good”. The collected data were later analyzed using comparison and intensity analysis, linear location and waveform analysis accompanied with pattern recognition, to identify series of hits with a particular event. Each event was investigated to determine if the type of damage, such as fiber breakage, matrix cracking, and delamination, could characterize the event. These types of events were the contributing factors to the investigated criteria and the structural performance of the specimens. Table A-3 summarizes the inherent characteristics and applications of AE method.

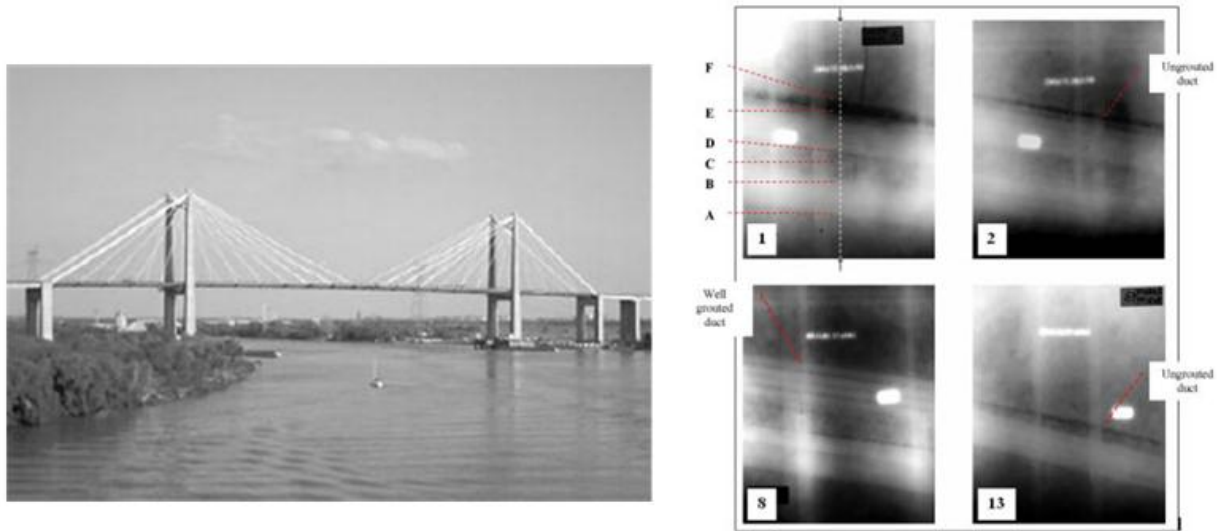
**Table A-3: Summary of Inherent Characteristics and Applications of Acoustic Emission Method**

<b>Advantages</b>	<b>Disadvantages</b>	<b>Best application case</b>	<b>Application with regard to duct type</b>
<ul style="list-style-type: none"><li>• Can indicate occurrence of a wire break, and may indicate its approximate location.</li><li>• Established technology.</li></ul>	<ul style="list-style-type: none"><li>• Expensive.</li><li>• Process generates large volumes of data that can be difficult to manage and interpret.</li><li>• Individual signal may be difficult to interpret or disrupted by noise, so some expertise is needed.</li><li>• Cannot detect existing damage.</li></ul>	<ul style="list-style-type: none"><li>• Locating breaks in external ducts (either plastic or metal).</li></ul>	<ul style="list-style-type: none"><li>• Possibly applied to both internal and external ducts, and in both metal and plastic ducts.</li></ul>

### **A.2.3 Radiography**

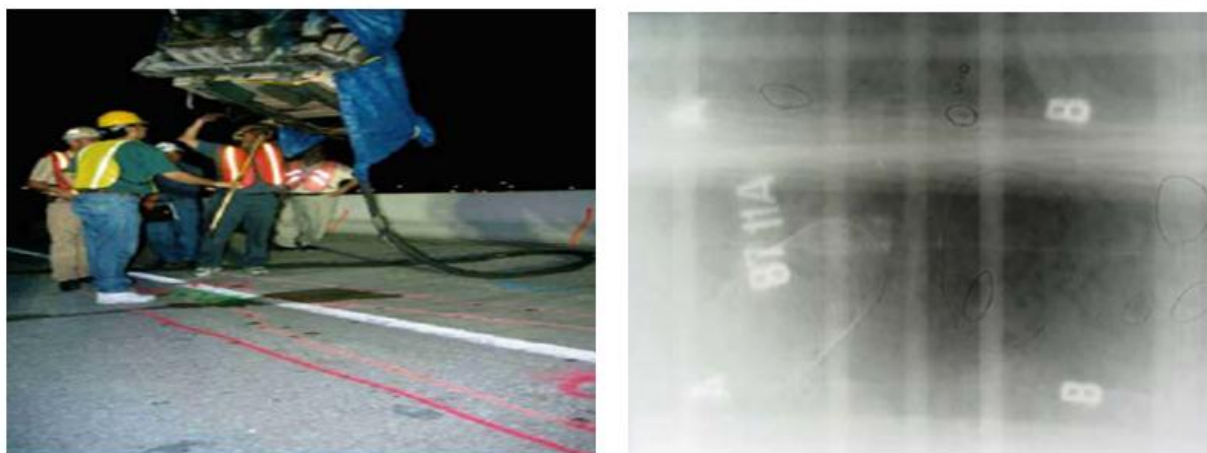
Radiography involves placement of an x-ray or gamma ray source on one side of the subject structure and a photographic film or digital detector on the other side of the structure. The radiation energy from the source penetrates the subject structure and exposes the film or detector. The amount of x-ray energy that passes through the subject material is related to the line average of mass density along the energy penetration path. The resulting radiograph image thus represents a map of density that varies across the material thickness. For example, areas of voiding in ducts show low density; metal tendons show high density, and grout is in between. This contrast allows for imaging of the conditions of both plastic and metal ducts. Portable linear accelerator x-ray sources used successfully for radiographic inspection of post-tensioning tendons or ducts in concrete have also shown success in detecting wire breaks and voids in stay cable laboratory specimens. X-ray radiography can also be used to image internal concrete conditions, including corrosion and void/grout conditions, of post-tensioning ducts. However, a primary drawback is radiation exposure hazard to people and the resulting cost needed to address this issue. Furthermore, it takes more time to apply this method than other NDE methods.

An inspection of a post-tensioned girder was carried out at the Zárate Bridge in Argentina. One of the 12-inch-thick girders at the west end of the bridge has a total of six grouted ducts. The ducts were inspected for voids in the grout using gamma-rays from a 93-curie  $^{192}\text{Ir}$  source. The obtained radiographs indicated severe voiding in the grouting in one of the upper ducts. Figure A.11 shows the study location and the x-ray radiographs from selected stay cables.



**Figure A.12: The Zárate Bridge (left); x-ray radiographs from selected stay cables, showing location of voids in the grout within the duct (right) (Mariscotti et al. 2009)**

X-ray radiography was applied to the post-tensioning system of Ramp D Bridge at the Fort Lauderdale International Airport, FL (see Figure A.12). The procedure was carried out with two technicians: one technician operated the x-ray equipment and the other set the film on the inside of the box girder. Inside the bridge, multiple 14"x17" sheets of film were arranged at each shot location to ensure that the picture was captured. Defects detected with the x-ray consisted of voids, damaged strands, damaged ducts, and flaws induced in the concrete. However, areas where the deck was saw cut and patched showed indications that required an additional level of interpretation.



**Figure A.13: X-Ray inspection of post-tensioned deck ramp D in Fort Lauderdale: x-ray inspection equipment (left) and example film radiograph (right) (DMJM Harris, 2003)**

Although the technology in its current state is very expensive and cannot be recommended for all inspection cases, it is likely that the technology will improve in the future due to mass production of sensors and become a good candidate for infrastructure inspection. Table A-4 summarizes the inherent characteristics and applications of radiography method.

**Table A-4: Summary of Inherent Characteristics and Application of Radiography**

<b>Advantages</b>	<b>Disadvantages</b>	<b>Best application case</b>	<b>What improvement can be made</b>	<b>Application with regard to duct type</b>
<ul style="list-style-type: none"> <li>• Can identify wire breaks and grout voiding.</li> <li>• Graphical output is easy to interpret</li> <li>• May be applicable to anchorage region.</li> </ul>	<ul style="list-style-type: none"> <li>• Significant safety and cost concerns.</li> <li>• Test geometry and access may be limited.</li> <li>• Radiograph gives no depth of field information</li> </ul>	<ul style="list-style-type: none"> <li>• Very broad application</li> </ul>	<ul style="list-style-type: none"> <li>• Can be improved by presenting data in 3-D visual format instead of a single radiograph</li> </ul>	<ul style="list-style-type: none"> <li>• Applicable to both internal and external ducts</li> </ul>

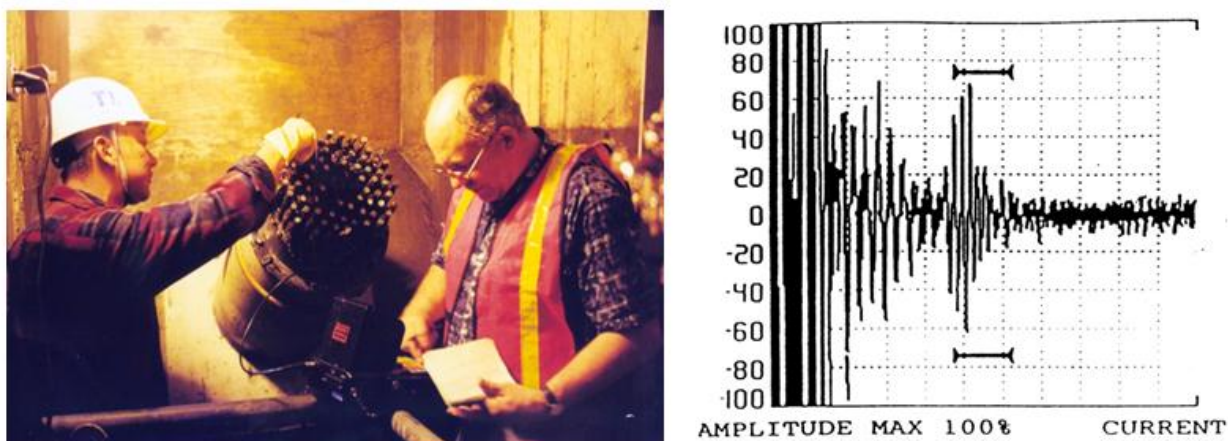


#### A.2.4 Ultrasonic Guided Waves

Ultrasonic guided wave testing (GWT) techniques were applied to detect hidden flaws such as wire breaks and grout voids in anchorage zones in the Cochrane Bridge in Mobile, AL, and the Talmadge Bridge in Savannah, GA (Mehrabi and Telang, 2003). Ultrasonic guided waves are structure-borne waves that propagate along a structural element, confined and guided by its geometric boundaries. The propagating waves reflect from any local cross-sectional area change, such as fiber breaks or corrosion defects. The GWT approach identifies defect location using the arrival time and the velocity of guided wave pulse, and estimates the defect size with the pulse amplitude. GWT uses relatively low-frequency waves (from 5 to 250 kHz) that have a long wavelength with respect to the tendon width in order to have less attenuation for long-range inspection. The application of ultrasonic GWT to tendons at the anchorage zone is shown in Figure A.13. Note that complete access to the ends of the tendons is required. The data are interpreted through time domain signals, where reflected pulses from fracture defects or other reflectors are located knowing the velocity of propagation of that particular guided wave packet. Table A-5 summarizes the inherent characteristics and applications of this method.

**Table A-5: Summary of Inherent Characteristics and Application of Ultrasonic Guided Waves**

<b>Advantages</b>	<b>Disadvantages</b>	<b>Best application case</b>
<ul style="list-style-type: none"><li>• Exciting potential to monitor tendon condition near ends and anchorage zones.</li></ul>	<ul style="list-style-type: none"><li>• Ends of tendons must be exposed and accessible.</li><li>• Complicated technology that can be difficult to apply properly.</li><li>• Frequency of waves must be adjusted to account for wave velocity and attenuation changes; as a result, the signals are difficult to interpret.</li><li>• Testing and analysis expertise are needed.</li></ul>	<ul style="list-style-type: none"><li>• Technology is not yet viable for application to embedded tendons in concrete.</li></ul>



**Figure A.14: Ultrasonic guided wave (at 50 khz) testing in progress (left) and a sample signal showing reflection from defect (right)**

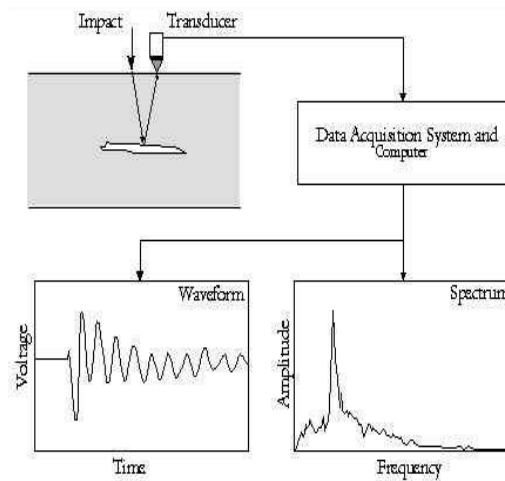
### **A.3 Methods to Detect Improper Grout Condition within Tendon or Cable Ducts**

The grouting condition inside of post-tensioned ducts is critical for the performance of post-tensioned and cable stayed structures. Improper grouting conditions, for example dry void formation, water intrusion, formation of unset or chalky grout, or use of contaminated grout, can promote accelerated corrosion of embedded strands. Thus NDT methods that can reliably characterize internal grouting condition and internal moisture content are needed.

#### **A.3.1 Impact Echo (IE)**

Impact-echo (IE) is a widely used NDT method that has been demonstrated to be effective for detecting defects in concrete structures. IE is a mechanical-wave method based on the transient vibration response of a plate-like structure subjected to mechanical impact. The mechanical impact generates body waves (e.g., P-waves or longitudinal waves and S-waves or transverse waves), and surface guided waves (e.g., Rayleigh surface waves) that propagate within the solid material. The multiply reflected and mode converted body waves eventually set up many vibration resonance modes within the solid material. The transient time response of the solid structure is measured with a contact sensor (e.g., displacement sensor or accelerometer) mounted on the surface close to the impact source. The Fourier transform (amplitude spectrum) of the time-signal will show maxima (peaks) at certain frequencies, which represent particular resonant modes, as illustrated in Figure A.14. The thickness stretch mode normally dominates the spectral response of a plate-like structure that does not contain any near-surface defects. In that case, the frequency of the fundamental thickness stretch mode ( $f$ ) can be related to the plate thickness ( $D$ ). Knowing the P-wave velocity  $V_p$  of concrete, the plate thickness  $D$  is related to the IE frequency by  $f =$

$\beta V_p/(2*D)$ , where  $\beta$  is a correction factor that depends on material properties of concrete, ranging from 0.945 to 0.957. The thickness stretch mode may also dominate the spectral response when the test is carried out over a relatively deep defect like a voided post-tension tendon duct.



**Figure A.15: Illustration of impact-echo test method (Sansalone & Streett, 1998)**

Olson Engineering and Dr. John Popovics of University of Illinois, have pioneered the development of impact-echo scanning systems, where impact echo data are readily collected over a large area and then presented in an image for effective interpretation. An effective application of Impact-Echo scanning systems is to locate voids in PT ducts with one-sided access for testing, where a drop in the impact-echo resonant mode is associated with the presence of an ungrouted duct.

Olson Engineering developed a scanning system based on a rolling transducer assembly incorporating multiple sensors. When the test unit is rolled across the testing surface, an opto-coupler on the central wheel keeps track of the distance. This unit is calibrated to impact and record data at intervals of 25 mm (1 inch). The maximum frequency of excitation of the solenoid impactors in the scanner is 25 kHz. The impactor in the scanning head can be replaced with one that generates higher frequencies if needed. Typical scanning time for a line of 4 m (13 ft), approximately 160 test points, is 60 seconds. In an Impact-Echo scanning line, the spatial resolution of the scan is about 25 mm (1 inch) between IE test points. Raw data in the frequency domain are first digitally filtered using a Butterworth filter with a band-pass range of 2 kHz to 20 kHz. Picks of dominant frequency were performed on each spectrum and an Impact-Echo thickness was calculated based on the selected dominant frequency. A three-dimensional plot (in either color or grayscale) of the condition of the tested specimens can also be generated by combining the calculated Impact-Echo scan lines. Figure A.15 shows the Olson impact echo scanning equipment, both handheld and vehicle mounted units.



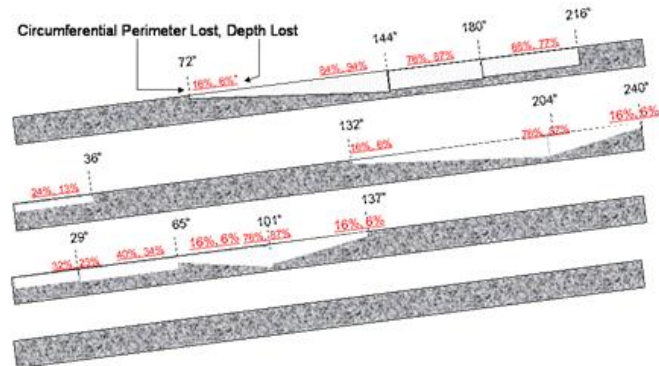
\*Note that tests can be carried out on rough unprepared concrete surfaces.

**Figure A.16: Olson impact echo scanning equipment: handheld unit (left) and vehicle mounted unit (right)**

NCHRP IDEA Contract 102 research involved a handheld impact echo scanning study to examine the method's sensitivity in identifying simulated void defects in grouted PT ducts, shown for a full-scale bridge girder in Figure A.16. Impact Echo tests were conducted vertically on the bridge web walls every 1 inch with test lines spacing 6 inches apart. As shown in Figure A.17, the void areas produced lower resonant echo frequencies that appear to give increased thicknesses of 11 to 14 inches. A parametric sensitivity studies was carried out with impact echo scanning on both steel ducts and plastic ducts with voids ranging from 11% area/volume to full cross-section voids. Table A-6 summarizes the inherent characteristics and applications of this method.

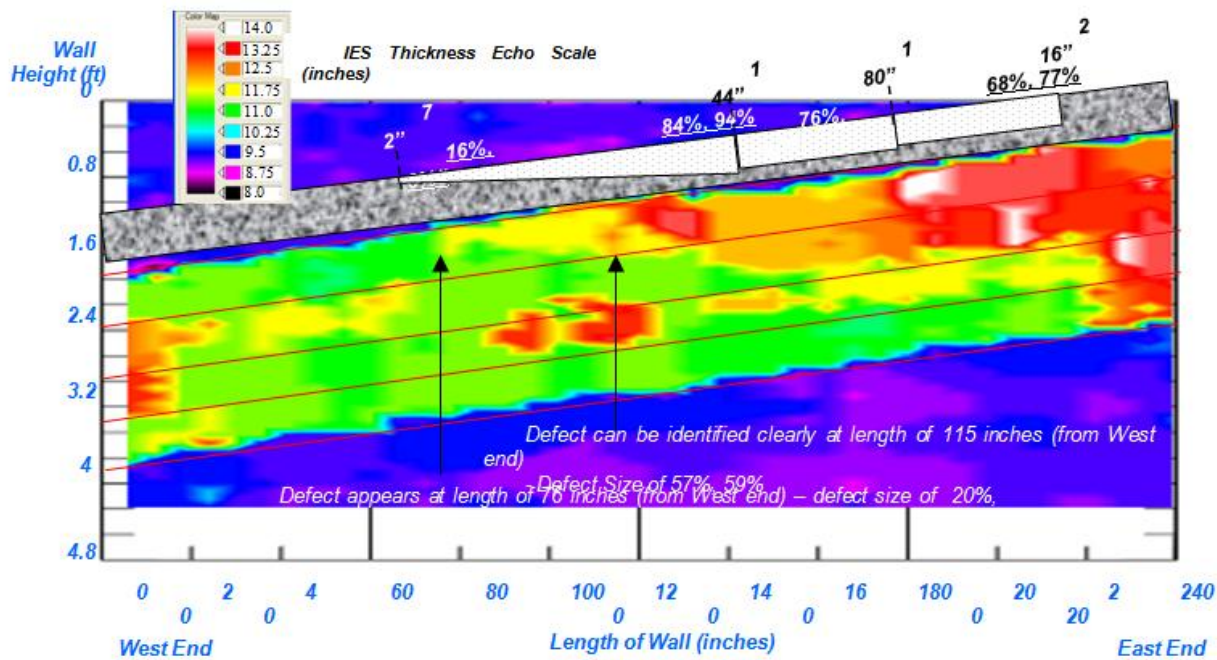
**Table A-6: Summary of Inherent Characteristics and Application of Impact-Echo Method**

Advantages	Disadvantages	Best application case	What improvement can be made	Application with regard to duct type
<ul style="list-style-type: none"> <li>• Can identify duct voids as an apparent reduction in thickness resonant frequency.</li> <li>• Established test.</li> <li>• Reported to be fairly sensitive.</li> </ul>	<ul style="list-style-type: none"> <li>• Signals may be difficult to interpret.</li> <li>• Some expertise needed.</li> <li>• Conventional tests (contact) can be slow.</li> <li>• Difficult to apply in anchorage region or for complicated element geometries.</li> <li>• May be less sensitive to voiding in plastic ducts.</li> </ul>	<ul style="list-style-type: none"> <li>• Detection of voids in internal metal ducts.</li> </ul>	<ul style="list-style-type: none"> <li>• Method can be improved with graphical image for data presentation.</li> </ul>	<ul style="list-style-type: none"> <li>• Applicable to internal ducts.</li> </ul>



**Figure A.17: Insertion of void (left) for Olson NCHRP idea 102 grant for impact echo scanning sensitivity research and grout/void defect plan built for south wall of PT bridge girder (right).**





**Figure A.18: Image created from impact-echo scan data collected with Olson equipment from the ie results from the south wall with actual design defects of top duct Orwell bridge. void areas are indicated by (apparent) increased thicknesses as shown in the thickness scale of 1**

### A.3.2 Acoustic Sounding (Hammer Tap)

Acoustic sounding is a simple and common NDT method applied to different bridge components, including external PT ducts and decks. In this method, an inspector taps the surface of a structure with a small hammer and then listens to the response. It relies on the experience of the inspector to differentiate the relative sounds generated when the hammer strikes the surface of the tested object: delaminated or voided areas are identified by a dull or hollow sound. Sounding inspection practice for bridge decks is covered in the ASTM D 4580-86 “Standard Practice for Measuring Delaminations in Concrete Bridge Decks by Sounding”. Sounding methods are not effective in detecting smaller defects. Although the sounding method is not expensive, it can be physically demanding for the inspector and time-consuming. Furthermore, the inspector must be familiar with the tonal differences between undamaged and damaged concrete and be able to distinguish the variations in the tones. Areas with high levels of background noise, such as those with large traffic volume or adjacent airports, industry, or construction sites, will make the sound variations difficult to distinguish. Table A-7 summarizes the inherent characteristics and applications of this method.

**Table A-7: Summary of Inherent Characteristics and Application of Acoustic Sounding Method**

<b>Advantages</b>	<b>Disadvantages</b>	<b>Best application case</b>	<b>What improvement can be made</b>	<b>Application with regard to duct type</b>
<ul style="list-style-type: none"><li>• Practical and relatively easy.</li><li>• Fairly accurate in detecting “dry” voids in the grout.</li></ul>	<ul style="list-style-type: none"><li>• Not sensitive to “soft” or unset grout.</li><li>• Subjective test that is operator dependent.</li></ul>	<ul style="list-style-type: none"><li>• External plastic duct looking for dry voiding in grout.</li></ul>	<ul style="list-style-type: none"><li>• Automate process and quantify results with acoustic sensors and appropriate data analysis.</li></ul>	<ul style="list-style-type: none"><li>• Applicable to external ducts only.</li></ul>

### **A.3.3 Impulse Response**

The Impulse Response test provides a record or signature of the structural (mechanical) compliance of a structure near a given test location. The testing apparatus consists of a hammer with an attached load cell, capable of generating small force at a point in the deck. The other element of the testing device is a surface-mounted transducer capable of measuring the response of the structure at relatively low frequency ranges; normally a geophone sensor (voltage output proportional to surface velocity) is used.

The IR testing is mainly used for condition assessment of bridge deck. However, it should also be applicable to external tendons. IR could also be used to assess the overall effect of corrosion in internal tendons on global response of structure.

Figure A.18 shows typical apparatus and controlling software used to conduct impulse response tests. The velocity transducer is placed at every defined testing grid point and an impact event from the hammer is applied nearby. The loading function data from the hammer and the response signal from the surface sensor are collected and processed. The time signal information is then converted to the frequency domain by using the Fast Fourier Transform (FFT). The resulting velocity spectrum is then divided by the force spectrum to obtain a transfer function, referred to as the “mobility” of the element under the test. Mobility is an index that allows the engineer to quickly assess the local compliance condition, which can be used to illustrate relative changes across the structure.



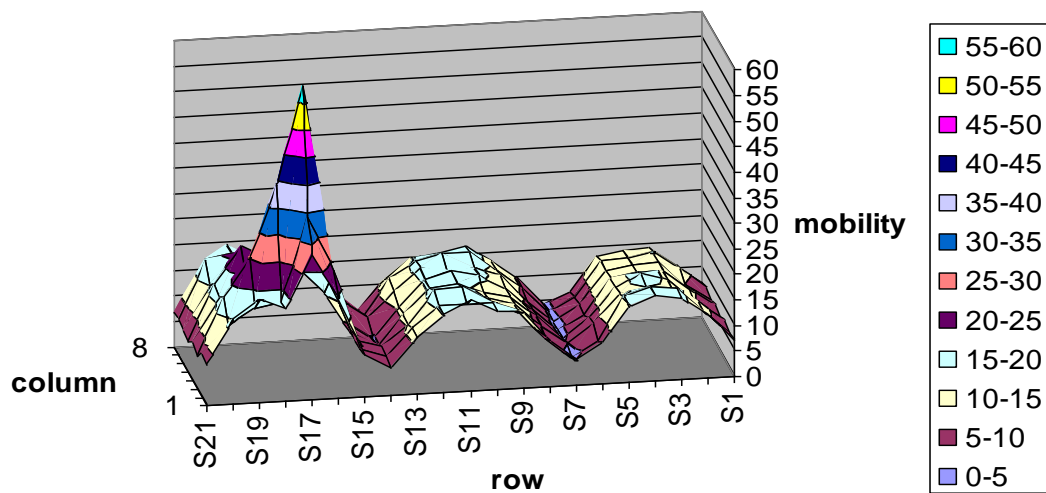
**Figure A.19: Impulse response test equipment (left) and data acquisition software showing sensor outputs and computed mobility signal**

Figure A.19 shows the results of the Impulse Response tests conducted on a segment of a bridge that included failed splice. In the figure, the axis labeled “row” lies along the bridge width, and the axis labeled “column” lies along the traffic lanes. The vertical axis is the mobility. In simple terms, the higher the mobility, the higher the tendency of the structure at that location to move (i.e., higher mechanical compliance). Higher mobility could be caused by damage or by being located in a portion of the structure with relatively lower stiffness. For instance in Figure A.19, the locations of low mobility at rows 1, 7, 14, and 21 coincide with bridge girders. The low mobility of the girders and the rigidity of the slabs would lead one to expect the slabs to also have low mobility. In the case of this particular bridge, between girders 14 and 21, mechanical devices were used for splicing the reinforcing bars. These mechanical devices had corroded and failed. As a result, one could note a relatively high mobility for the portion of the slab between girders 14 and 21. These results exhibit the capabilities of the IR testing. It should be viewed as a means to gain more insight into the condition of the structure. It could also be used to assess the condition of the same structure over time by repeating the test over the same area and studying the changes in mobility. An increase in mobility would be an indication of increased damage to the area. Table A-8 summarizes the inherent characteristics and applications of this method.



**Table A-8: Summary of Inherent Characteristics and Application of Impulse Response**

Advantages	Disadvantages	Best application case	Application with regard to duct type
<ul style="list-style-type: none"> <li>Potential to measure mechanical compliance of a duct system, which could reflect a duct grouting or other problem.</li> </ul>	<ul style="list-style-type: none"> <li>Probably not sensitive to small defects.</li> </ul>	<ul style="list-style-type: none"> <li>External ducts with large void in grout.</li> </ul>	<ul style="list-style-type: none"> <li>Probably applicable only to external ducts, giving one global value for entire duct.</li> <li>Unlikely to work for internal ducts unless void is very large.</li> </ul>

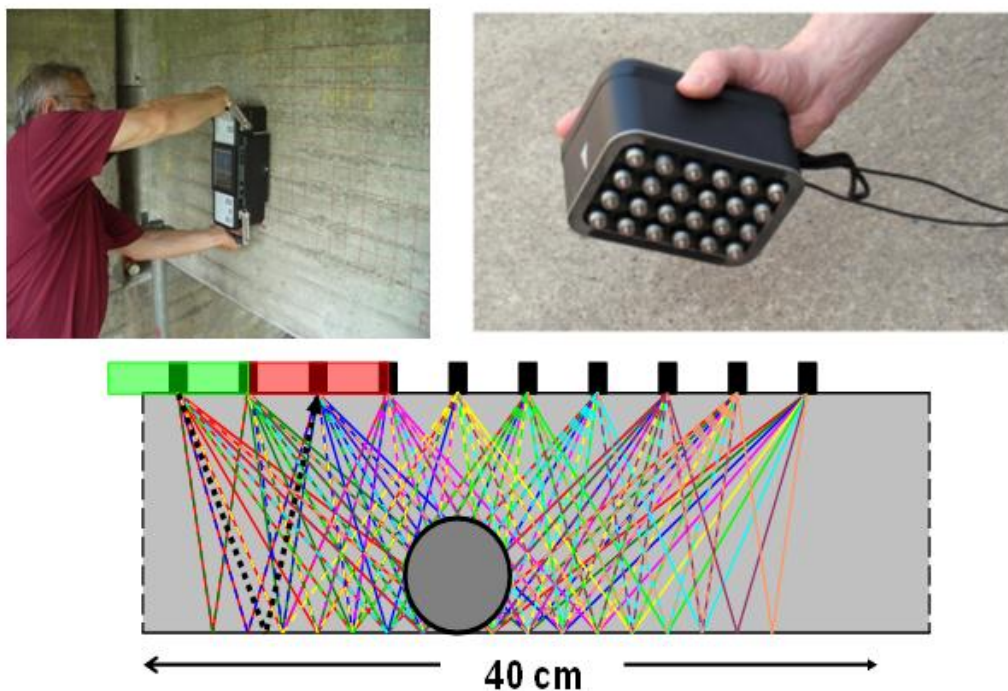


**Figure A.20: Obtained IR mobility plot collected from a segment of a post-tensioned bridge. Locations of corrosion and damage are indicated by high mobility value.**

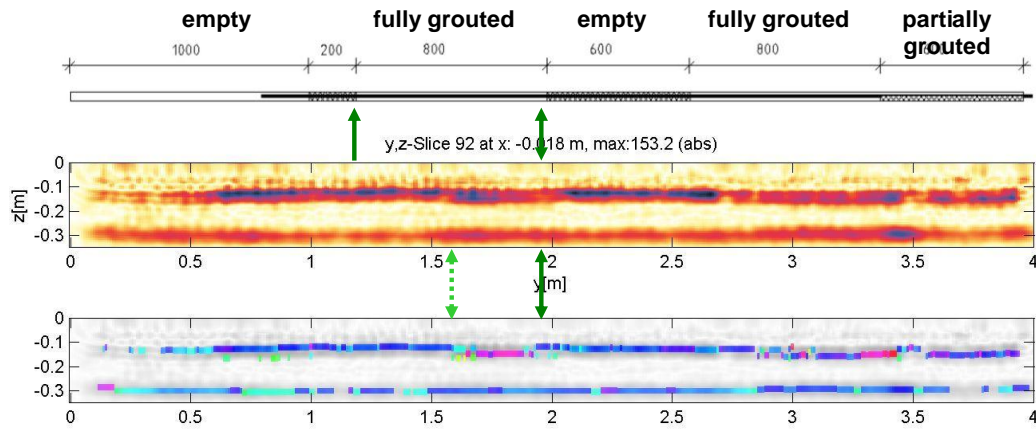
#### A.3.4 Ultrasonic Imaging

Recent advances in ultrasonic array transducer technology have promoted the development ultrasonic imaging capability in concrete. One such development is the shear wave (s-wave) dry point contact transducer array, shown in Figure A.20. Each of the point transducers that are in contact surface and do not require any coupling material between transducer and surface can send and receive an s-wave. As a result, multiple intersecting s-wave wave paths can be generated across the transducer array set underneath the footprint of the array set; see Figure A.20.

Once the intersecting data set is collected, it is processed using the synthetic aperture focusing technique (SAFT). In SAFT, multiple linearly spaced time signals from each S-wave transducer are shifted in time to superpose on a coherent wave reflection within the sound field. A coherent wave reflector represents some inclusion, for example, an air void within concrete that is revealed as an indication within a cross-sectional slice image of the material. The images obtained with commercially available equipment indicate wave reflecting targets but are not able to distinguish further characteristics about the reflector, for example if a tendon duct is grouted or empty. However, recent signal processing developments in Germany allow further characterization of SAFT images built up from s-wave array data, by using the phase information of the received wave pulses. Figure A.21 illustrates this development; conventional SAFT images and phase modified SAFT images are presented from data collected from a post-tensioned concrete element using s-wave array sets.



**Figure A.21: Illustration of ultrasonic s-wave array equipment (top) and data collection scheme (bottom)**



**Figure A.22: Illustration of conventional SAFT image (top) and phase modified SAFT image (bottom) collected from a PT girder. The color indicates the phase of the reflected wave in the phase modified image.**

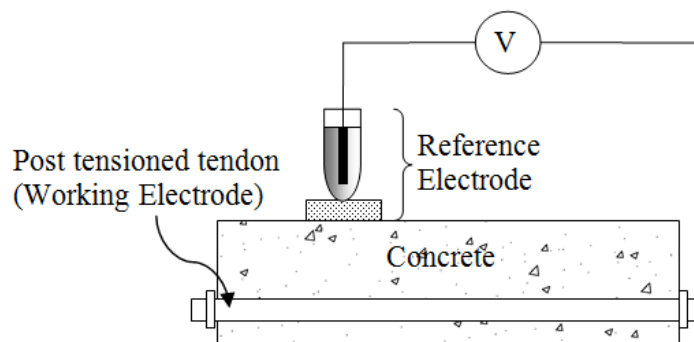
Both images indicate the presence of the PT duct within the element, but the phase modified image is able to further characterize the duct as either filled or empty. However, it should be noted that signal processing and imaging technology is not yet available in commercial s-wave testing equipment packages. Recent advances in fully air-coupled ultrasonic tomographic imaging for concrete members have also been reported by Popovics; he reports that internal voiding can be detected in concrete using this approach. However, fully air-coupled ultrasonic tomography is still a developing technology, and thus is relegated to the laboratory environment and not yet ready to be applied in the field. Table A-9 summarizes the inherent characteristics and applications of this method.

**Table A-9: Summary of Inherent Characteristics and Application of Ultrasonic Imaging**

<b>Advantages</b>	<b>Disadvantages</b>	<b>Best application case</b>	<b>What improvement can be made</b>	<b>Application with regard to duct type</b>
<ul style="list-style-type: none"> <li>• Can be used to identify internal reflectors within concrete, including ducts.</li> <li>• Graphical output is easy to interpret.</li> <li>• May be applicable to anchorage region.</li> </ul>	<ul style="list-style-type: none"> <li>• May be difficult to distinguish voided from filled ducts with commercially available equipment.</li> </ul>	<ul style="list-style-type: none"> <li>• Location of internal ducts, both plastic and metal.</li> </ul>	<ul style="list-style-type: none"> <li>• Improve data analysis and data presentation to better identify voided ducts (e.g., using phase information).</li> </ul>	<ul style="list-style-type: none"> <li>• Applicable to internal ducts, both metal and plastic.</li> </ul>

#### **A.4 Methods to Detect Active Corrosion of Tendon or Cable**

Methods that monitor active corrosion normally make use of the electrochemical basis of the process. Most electrochemical techniques use the same measurement set up. It consists of a reference electrode, a working electrode, a counter electrode, and a volt meter as shown in Figure A.22. Note that a closed electrical circuit is required, so direct electrical connection to the inspected steel is required.



**Figure A.23: Fundamental measurement setup for electrochemical techniques**

Only laboratory studies have been conducted so far to check the feasibility of electrochemical techniques for detecting corrosion in post-tensioned strands. The most significant electrochemical test procedures are summarized in Table A-10 and in the following sections.

**Table A-10: Summary of Inherent Characteristics and Applications of Electrochemical Methods**

<b>Advantages</b>	<b>Disadvantages</b>	<b>Best application case</b>	<b>What improvement can be made</b>	<b>Application with regard to duct type</b>
<ul style="list-style-type: none"> <li>• Potential to measure meaningful data related to active corrosion of strand.</li> </ul>	<ul style="list-style-type: none"> <li>• Electrical connection to tendon is required.</li> <li>• Sensors must be placed within the duct to monitor tendon.</li> <li>• Difficult to apply to the existing PT ducts with current available technology because of the requirement that sensors must be inside the duct.</li> </ul>	<ul style="list-style-type: none"> <li>• Standard steel reinforcing bar and tendon systems in concrete not within ducts.</li> </ul>	<ul style="list-style-type: none"> <li>• Develop robust sensors and sensing systems that are applicable within ducts.</li> </ul>	<ul style="list-style-type: none"> <li>• Probably not applicable to external or internal ducts at this time</li> </ul>

#### **A.4.1 Half-cell Potential**

The half-cell potential test uses an external half-cell electrode and a voltmeter to detect the voltage differential within the embedded steel reinforcement. The magnitude of the voltage differential has been found to be an indicator of corrosion likelihood. For conventional reinforcing steel in concrete, a voltage potential of less than -350mV (assuming a copper-copper sulfate reference electrode) is an indicator of likely corrosion activity. This value is not definitive, and cannot be used to determine the actual corrosion rate. Furthermore, the data are less reliable for prestressing steels, for large concrete covers, and for concrete with certain constituents. Photos of half-cell potential equipment are shown in Figure A.23.

A field application of half-cell potential to a post-tensioned system is now described. The tests were conducted using a copper electrode in a copper sulfate solution. A prefabricated probe produced by Elcometer was used along with a Fluke digital multimeter to measure voltage as shown in Figure A.23. Electrical connection to the strands was established by access through broken concrete covers at the end of the box beams. In order to wet the beams, soaked burlap pieces were placed over the beams. The burlap pieces were then covered with a plastic tarp.



Half-Cell Electrode with Multimeter

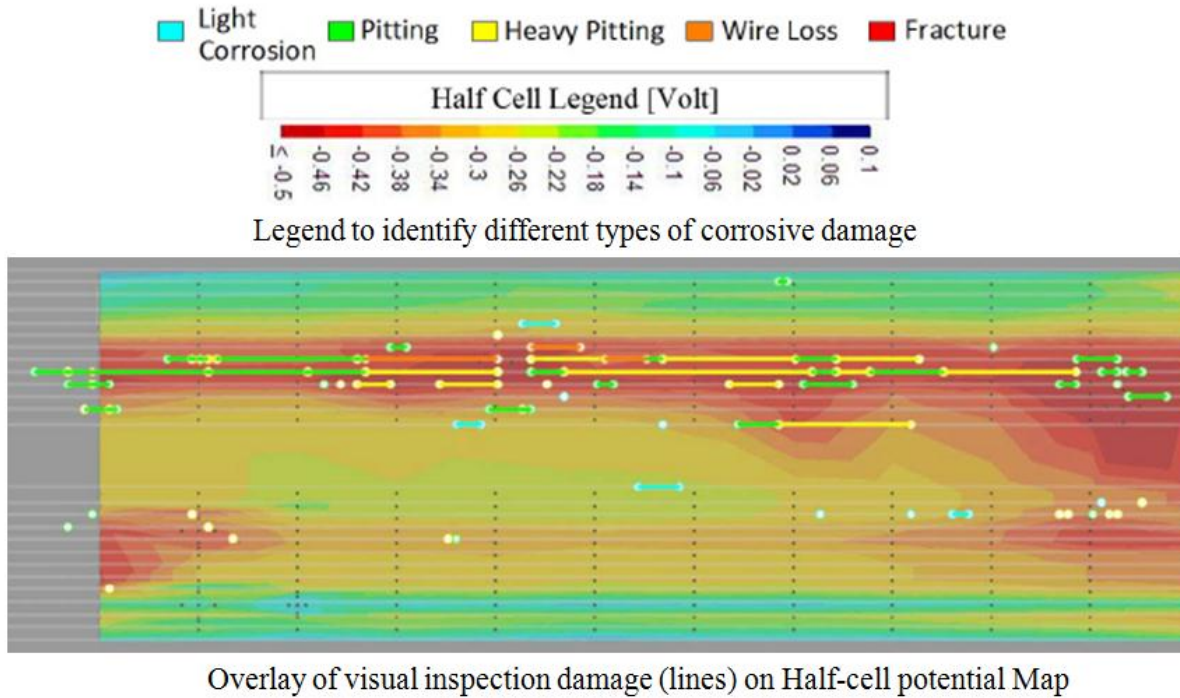


Electrical connection to strands

**Figure A.24: Half-Cell measurement equipment and connection setup (Naito et al. 2010)**

To assess the effectiveness of the half-cell potential method, the strand damage profile has been overlaid on the half-cell contour for each beam. As shown in Figure A.24, the damage detected by visual inspection was spread throughout a cracked region just above the centerline of the beam. The highly cracked region shows voltage reading that indicate corrosion.





**Figure A.25: Evaluation of corrosion detection ability of half-cell measurement (Naito et al. 2010)**

The average half-cell reading tends to increase with the severity of damage. While the half-cell measurement and the in situ strand corrosion damage were correlated, the coefficient of variation (COV) was large: the COV values for different levels varied from 25% to 56%. Therefore, while half-cell potential provides an indication of corrosion damage, it should not be explicitly applied to predict the particular type of damage.

#### A.4.2 Linear Polarization Resistance (LPR)

LPR is a method to determine the instantaneous corrosion rate in metal. LPR was developed to enable accurate assessment of the condition of the reinforced concrete structures. In LPR, steel is slightly perturbed electrically from its equilibrium potential. This can be accomplished either potentiostatically, by changing the potential by a fixed amount  $\Delta E$  and monitoring the current decay  $\Delta I$  after a fixed time, or galvanostatically, by changing the current by affixed amount  $\Delta I$  and monitoring the potential decay after a fixed time. In both cases, conditions are selected in such a way that potential  $\Delta E$  falls within Stern-Geary range of 10-30 mV. Polarization resistance  $R_p$  is calculated by

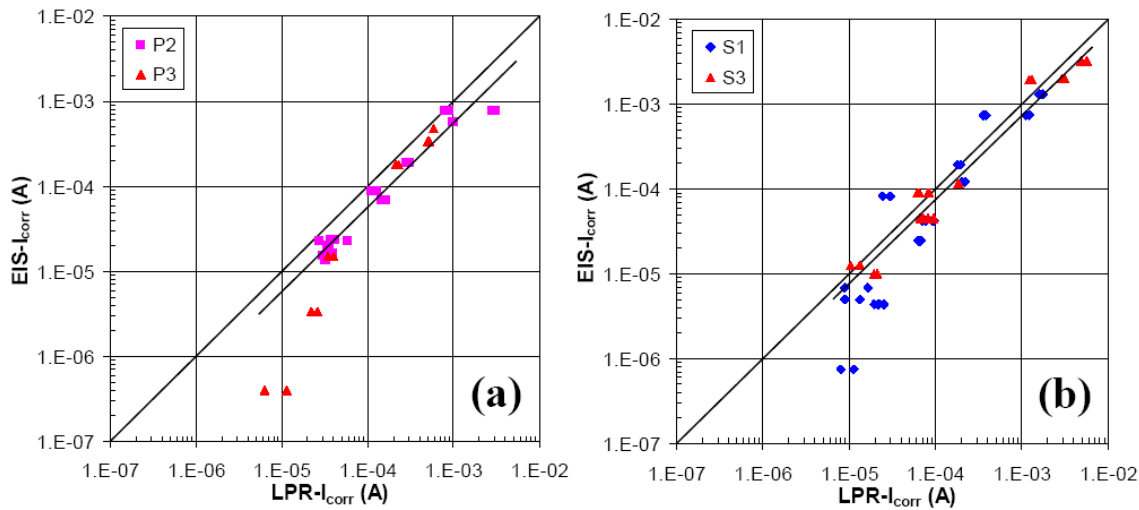
$$R_p = \Delta E / \Delta I.$$

The rate of corrosion,  $I_{corr}$ , is calculated as

$$I_{corr} = B / R_p$$

where  $B$  is the Stern-Geary constant.

LPR measurements have been applied to post-tensioned tendon assemblies and compared to electro-impedance spectroscopy (EIS) tests conducted on the same samples. The results are shown in Figure A.25, and indicate good agreement between the two methods.

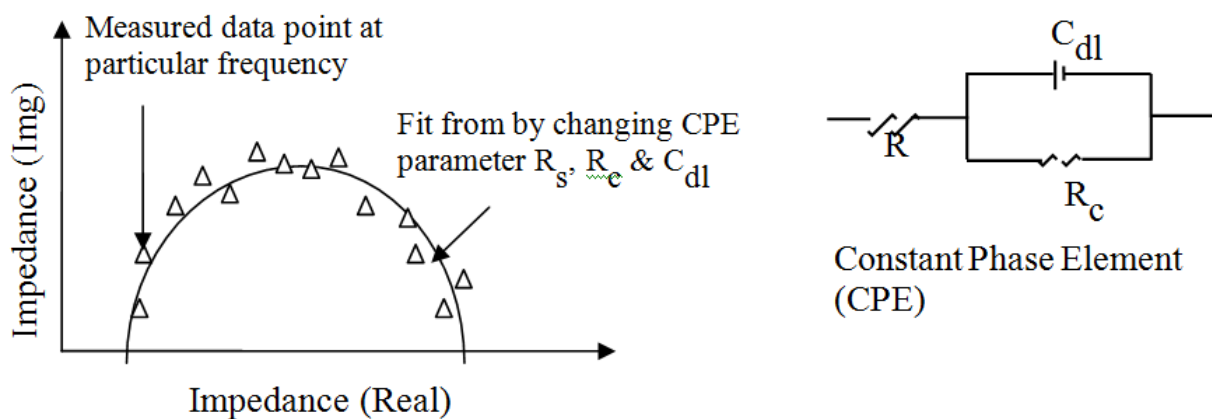


**Figure A.26: Comparison of total  $I_{corr}$  estimated by EIS and LPR for (a) P and (b) S assemblies. (Taveira et al. 2008)**

#### A.4.3 Electro-Impedance Spectroscopy (EIS)

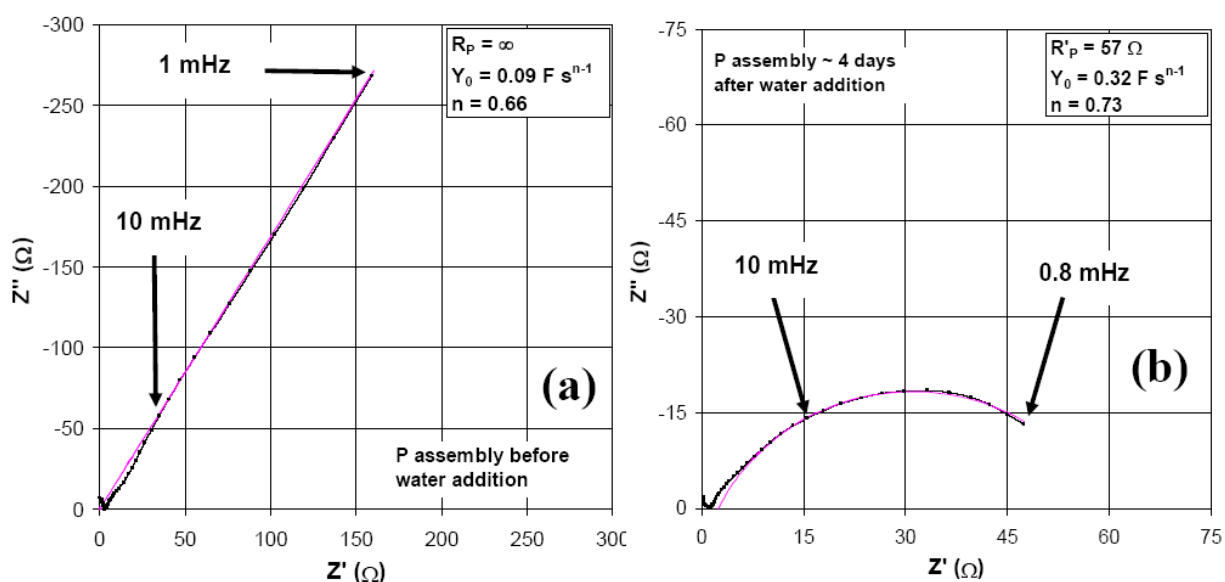
In this technique a small amount of alternating current (AC) with a particular frequency is applied to a metal-electrolyte interface. Amplitude and phase shift data of the resulting current are measured to calculate the impedance of the interface between concrete and steel. Impedance is a complex number having a real part (resistance) and imaginary part (capacitance). Impedance is calculated for different frequencies of AC. Real and imaginary parts of impedance are plotted for different frequencies as shown in Figure A.26. An equivalent circuit can be defined with parameters ( $R_s$ ,  $R_c$  &  $C_{dl}$ ) as shown in Figure A.26. Values of these parameters are adjusted to best fit the measured data. Selection of circuit parameters depend on the nature of the data.





**Figure A.27: Impedance spectrum (left) and electrical circuit (right) assumed to fit the spectrum data (Taveira et al. 2008)**

Figure A.27 shows EIS data from a grouted assembly before and after a water recharge event. The solution resistance ( $R_s$ ), which corresponds to the grout resistance, is in series with the parallel combination. The value of  $R_s$  is obtained by fitting the impedance predicted by such analog circuit to the actual impedance results, considering all data in the 1 mHz to 100 Hz frequency interval.



**Figure A.28: EIS behavior of p1 assembly (a) before and (b) after a water recharge event. the estimated electrochemical parameters are shown in the graph. (Taveira et al. 2008)**

The corrosion currents  $I_{\text{corr}}$  are estimated by the Stern-Geary relationship, where polarization resistance  $R_p = R'_p + R'_s - R_s$ .  $R'_p$  and  $R'_s$  are obtained by performing the fit only for the lowest 10 frequency data (using frequencies  $< 1\text{MHz}$  when available) in the impedance spectrum

$$I_{\text{corr}} = \frac{0.026}{R_p}$$

Nominal corrosion rate is calculated by

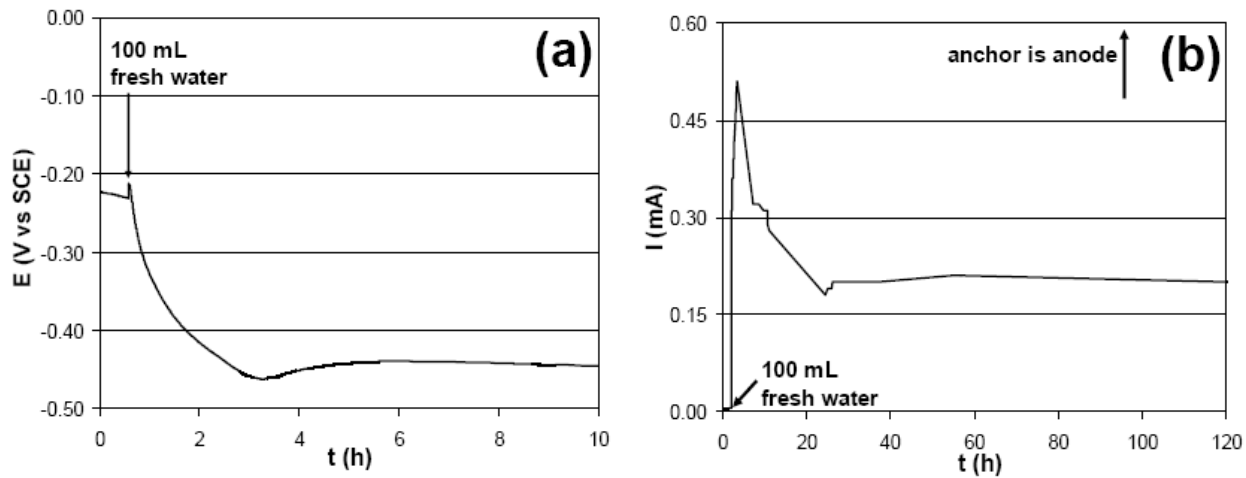
$$\text{Corrosion rate } \left( \frac{\mu\text{m}}{y} \right) = \frac{I_{\text{corr}} m_{\text{eq}} 3.15 \times 10^{11}}{\rho 96500 A}$$

where  $A$  = area of metal in contact with grout, and is equal to  $1000 \text{ cm}^2$ ,  $m_{\text{eq}}$  = the equivalent weight of  $\text{Fe}$  ( $27.92 \text{ g/equivalent}$ ), and  $\rho$  = the density of  $\text{Fe}$  ( $7.87 \text{ g/cm}^3$ ).

#### **A.4.4 Electrochemical Noise (EN)**

In this technique fluctuations in open circuit potential and current are measured as the system corrodes. It is mostly used to detect pitting corrosion. During the initiation and nucleation stages of pitting corrosion, there is a rapid potential drop as electrons accumulate at the metal surface due to the dissolution of metal during a predominantly initial anodic stage. This potential drop is reflected in EN signal as shown in Figure 28. This stage terminates by pit repassivation or some other anodic stage. After repassivation, a predominantly cathodic stage takes place.

Experimental results for post-tensioned tendons are shown in Figure A.28. Both current and potential show a clear decrease after addition of fresh water for P assemblies as shown in Figure A.28. For S assemblies this clear drop was not noticed.



**Figure A.29: (a) Potential and (b) current trends of anchor-strand system for p3 assembly (the arrow indicates the water addition) (Taveira et al. 2008)**

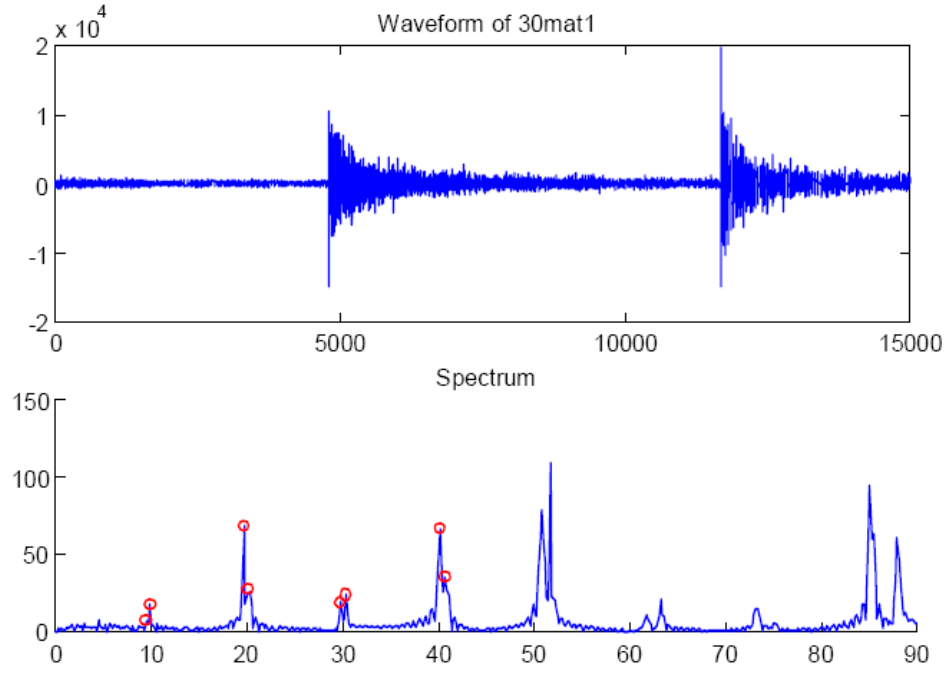
## **A.5 Methods to Characterize In Situ Tension Force within a Cable or Tendon**

The tension force level sustained by a cable or tendon is critical for the performance of post-tensioned and cable stayed structures. Furthermore, a difference of tension at opposite ends of tendons, low stiffness, and low tension indicate the presence of defects within the system. Thus NDT methods that can reliably characterize sustained tension level within post-tensioned and cable stay systems are needed.

### **A.5.1 Vibration Response Monitoring for Ducts**

This method was initially developed to assess condition of post-tensioned tendons of segmental bridges. The vibrational response of tendons subjected to mechanical excitation is monitored in this technique, where the vibrational response is analyzed to estimate the tendon tension and stiffness.

A field application of this method to an externally post-tensioned structure, the Niles Channel Bridge, is now described. A ‘dead-blow’ hammer was used, hitting perpendicular to the tendon axis. Each tested tendon segment extended from the edge of the externally protruding portion of the metal duct nearest to the end of the span, to the edge of the duct at the first deviation saddle from the span end (clear length denoted  $L$ ). The impact point was at a distance  $1/6 L$  from the edge of the duct nearest to the end of the span. A single-axis accelerometer positioned at a distance  $1/3 L$  from the edge of the duct was used to measure vibrational modes shown in Figure A.29. Fast Fourier Transform (FFT) analysis was carried out to determine the resonant frequency and overtones.



**Figure A.30: Example of waveform data recorded by accelerometer and FFT analysis (Sagüés & Kranc 2000)**

In the obtained spectrum, all peaks having amplitude twice the noise background were identified and their frequency value measured. Further peak frequency sequence was fit to a polynomial and points deviating substantially from the smooth curve were also rejected. To analyze the processed spectrum, the vibrating tendon segment was modeled as a dynamic system. The length of the segment was assumed to be equal to the distance between steel pipe rims at each end. End constraints were treated as clamped. The tendon cross section was treated as a uniform material equivalent to the composite arrangement.

The system as described is governed by a fourth order differential equation

$$T \frac{\partial^2 y}{\partial x^2} - S \frac{\partial^4 y}{\partial x^4} = \rho A \frac{\partial^2 y}{\partial t^2}$$

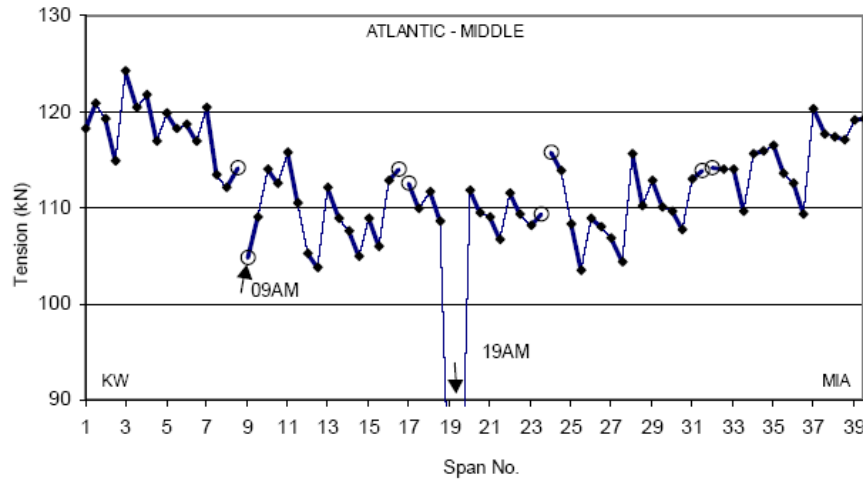
where:

$x$  = length coordinate,

$y$  = in-plane deflection of tendon,

- $\rho$  = density of steel,  
 $S$  =  $QA\kappa^2$  = the effective stiffness,  
 $Q$  = effective modulus of tendon,  
 $A$  = cross sectional area of tendon, and  
 $\kappa$  = radius of gyration of tendon.

Using the redundant multiple peak information, both  $T$  and  $S$  were obtained as outputs of a numerical solution procedure. Tensions in tendons are plotted as a function of bridge position as shown in Figure A.30. Tendon 19AM (Atlantic Middle) had tension values dramatically lower than any other in the bridge. The data for that tendon are indicated by arrow. However, the electrical tests on this tendon did not reveal distinctive behavior. Yet in some cases, damage indicated by low tension values was confirmed by electrical measurements. The advantages and disadvantages of this method are given in Table A-11.



**Figure A.31: Tendon segment tension plotted as a function of position along the bridge (Sagüés & Kranc 2000)**

**Table A-11: Summary of Advantages and Disadvantages of Vibration Response Monitoring Technique**

Advantages	Disadvantages
<ul style="list-style-type: none"> <li>• Suitable for quick scanning.</li> </ul>	<ul style="list-style-type: none"> <li>• Cannot detect corrosion.</li> <li>• From the report above, it can be said that in some cases, results are not verified by other techniques in case of post tension tendons.</li> <li>• Only very large structural defect like breaking of tendon can be detected successfully.</li> <li>• Vibration characteristics of tendons can be affected by temperature changes and bridge live loads.</li> </ul>

### **A.5.2 Global Vibration Frequency Monitoring for Stay Cables**

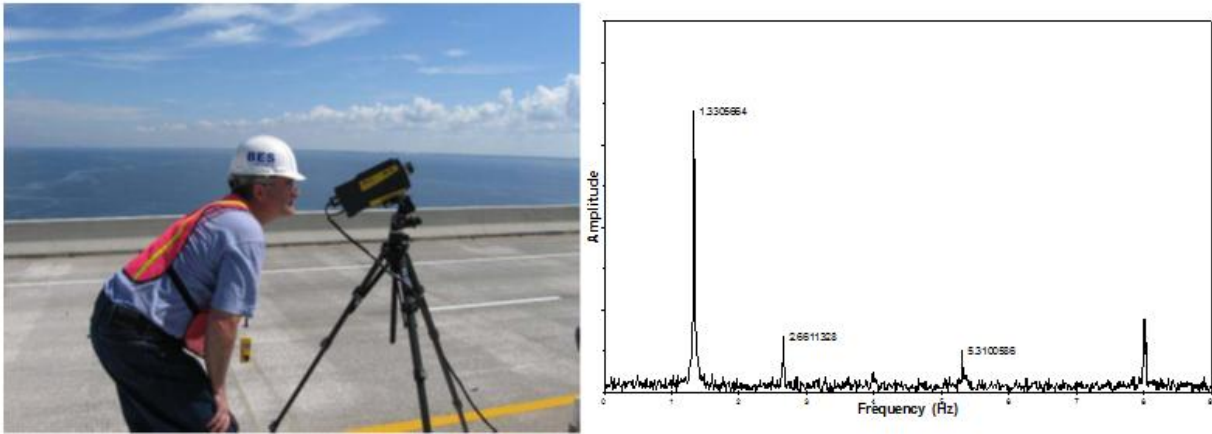
A number of conventional approaches to measure stay cable forces in an actual structure are available. But these methods are, in one or another way, costly, disruptive, time consuming and often not accurate enough for force monitoring or bridge quantitative evaluation purposes. A rapid, nondestructive technique for assessment of cable forces is desirable and could provide a convenient and cost-effective tool for stay cable safety evaluations. This approach utilizes preliminary inspection, and force and damping measurement techniques (using laser system or other sensors) to evaluate the global integrity and structural safety of a cable-stayed element with relatively minimal effort. The stay cable force array, when combined with analytical interpretation of the force changes, provides clear indications of location, type, and intensity of significant damages detected by this technique (Mehrabian et al., 1999). These provide bridge owners a rapid, cost effective, and highly reliable tool to address their immediate concerns and to determine the need for action. Monitoring changes in stay cable forces over time provides an indirect method for detecting loss of stiffness or cross-section due to fracture or corrosion (Mehrabian 2006). However, the effectiveness of this method is restricted to detection of significant levels of damage to cross-section, e.g., wire or strand breaks. Force measurement results can also point to a need for the investigation for local damage detection and its potential suspect locations.

One of the techniques most frequently used for tension element force measurement is vibration-based force measurement. In the vibration technique, the dominant vibration frequencies of cables are calculated from the vibration time histories recorded in the measurement process. The tension force is then estimated based on the dominant frequencies through mathematical relationships. This technique has a theoretical basis and has been used for force measurement of various types of cable structures. The method adapts the basics of the physics theory for vibration of taut strings. Due to the complex nature of the problem of free vibration of cables with vibration characteristics different from strings, accurate yet simple analytical relationships that take into account all pertinent parameters are still not available. In many cases (such as stay cables), the use of the string equation leads to excessive oversimplification and unacceptable increased errors in force prediction.

Field applications of vibration-based methods may pose problems related to the attachment of sensors (accelerometers) to measurement points, such as interruption of bridge function and traffic flow. For periodic cable force measurements, the manual method of sensor attachment involves additional cost and difficulty. Thus there are many advantages of using remotely located contactless monitoring technology, so this approach is recommended for periodic force measurement of cables. It eliminates the need to access the cables for sensor installation and normally avoids major interruption to traffic. However for continuous force and frequency measurement, installation of vibration sensors still should be considered. Several different contactless sensing technologies are now available to monitor stay cable vibration: an optical (laser vibrometer) approach and a high frequency pulsed radar (e.g., the IBIS system) approach. The latter provides some advantage in that multiple cables can be monitored simultaneously from one measurement position. In most cases, ambient excitation sources, such as traffic and wind induce enough vibration, and there is often no need for manual excitation. However, if these sources are not present, cables must be excited manually. Depending on accessibility and cable stiffness and size, manual excitation can be performed with light impact event or the use of ropes, where a rope is passed around the cable and pulled repeatedly with a rhythm in concert with cable's natural vibration frequencies.

Application of the optical laser vibrometer for vibration-based method measurement of stay cables is shown in Figure A.31. Mehrabi has completed and enhanced this technique by developing a mathematical formulation and simplified relationships that take into account the effect of parameters that were not considered in existing taut string equations. This technique has been validated by extensive laboratory experimentation and field verification sponsored by FHWA, and has been used

successfully for more than a decade for evaluation of more than twenty bridges. Table A-12 summarizes the inherent characteristics and applications of this technique.



**Figure A.32: Laser vibrometer system for force measurement of tension elements (left) and a measured frequency spectrum characterizing the cable vibration (right).**

**Table A-12: Summary of Inherent Characteristics and Application of Global Frequency Monitoring Technique**

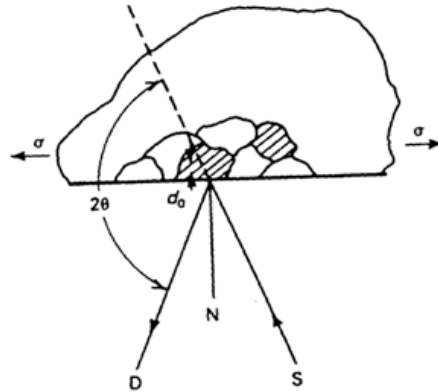
Advantages	Disadvantages	Best application case	Application with regard to duct type
<ul style="list-style-type: none"> <li>• Rapid and convenient contactless technique.</li> <li>• Large defects can be detected.</li> </ul>	<ul style="list-style-type: none"> <li>• Not sensitive to small ducts.</li> </ul>	<ul style="list-style-type: none"> <li>• Monitoring of stay cable performance by relative comparison.</li> </ul>	<ul style="list-style-type: none"> <li>• Applicable mainly to cable stays, although possibly applied to external post-tensioned ducts.</li> </ul>

### A.5.3 X-Ray Diffraction

The x-ray diffraction is a commonly used technique to measure stresses in thin metal lines and interconnects on semiconductor devices. X-ray stress measurements are used to help solve material failure problems, check quality control, verify computational results, and contribute to fundamental materials research. It precisely determines the distance between planes of atoms in crystalline material through the measurement of peak positions. The positions are then used to determine the elastic strains which can be converted to stresses using appropriate elastic constants. Plastic deformation can be detected through changes in diffraction peak widths rather than peak shifts. Figure A.32 shows the



diffraction of a monochromatic beam of x-rays at a high diffraction angle ( $2\theta$ ) from the surface of a stressed sample.



**Figure A.33: Principles of X-ray diffraction stress measurement (Paul S. Prév y, 2002)**

X-ray diffraction for direct stress measurements has its strong and weak points. Their relevance varies strongly from application to application, and needs to be considered for each application separately. In order to do so, the strengths and limitations are discussed below.

The main strengths of x-ray diffraction for direct stress measurements are:

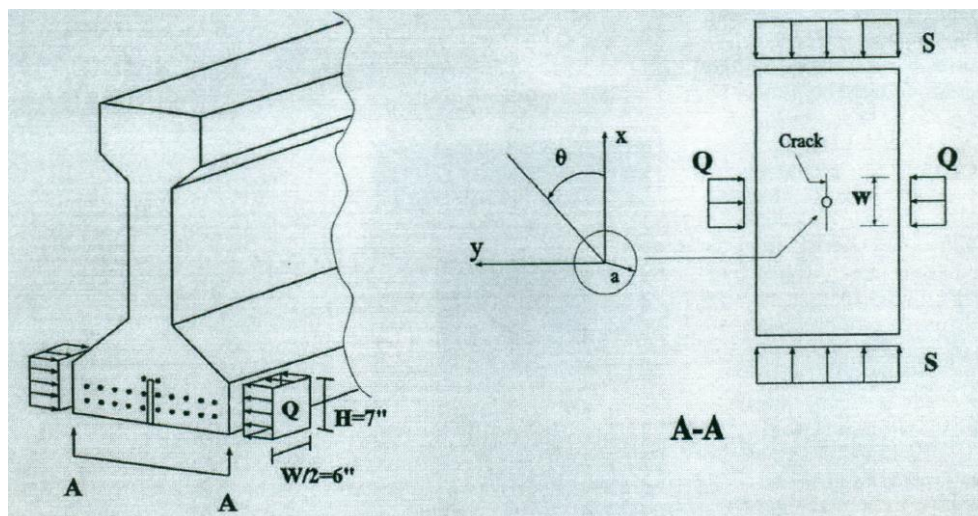
- determination of the depth and magnitude of the compressive layer and hardness produced by carburizing steels,
- investigation of the uniformity of the surface compressive residual stresses produced by shot peening in complex geometries,
- measurement of surface residual stresses and hardness on the raceway of ball and roller bearings as functions of the hours of service,
- study of the alteration of residual stress and percent cold work distributions caused by stress relieving heat treatment or forming,
- measurement of surface and subsurface residual stresses parallel and perpendicular to a weld fusion line as a function of distance from the weld, and
- determination of the direction of maximum residual stress and percent cold work gradient caused by machining.

#### A.5.4 Direct Prestress Measurement

A direct prestress measurement technique was first introduced by Hansen and Overman in 1980s at Construction technology Laboratories, where the P.I. was employed from 1985 through 1989. In the 1990's, the P.I. conducted (Azizinamini, A., Keeler, B, Rohde, J., Mehrabi, A, (1996)) research and developed the direct stress measurement nondestructive testing method. He applied it to prestressed girders to directly measure the available prestress in existing girders. The accuracy of the method is excellent.

This technique can accurately measure the available prestress forces in the strands. Its effectiveness in determining the prestress force measurement and making conclusions about corrosion activities in embedded steel elements, such as strands in duct, has not been investigated. In the opinion of the P.I., this technique could be part of a hybrid approach in corrosion inspection strategy. It is feasible to modify the technique and apply it to stays, ropes, and external tendons. This method, in its modified and new form, has been used to accurately measure (within 3%) the available prestress in existing prestressed girders. The following section provides an overview of the direct force measurement technique, its development and application.

The method is based on an investigation of the state of stress around a hole in a prestressed concrete member. In this method, a cylindrical hole is drilled in the bottom flange of a prestressed girder (assumed to be under compression), as shown in Figure A.33.



**Figure A.34: Sectional view of a prestressed concrete girder (Azizinamini et al. 1996)**

The stress  $S$  can be viewed as the available prestress in the bottom flange of the prestressed girder. The side pressure  $Q$  could be a known applied pressure over a width  $W$  and depth  $H$ . The main objective is to determine the axial stress  $S$ . This requires the knowledge of the hoop stress  $t_{ii}$ , and the concentration factors  $\beta$  and  $\gamma$ . Determining the hoop stress  $t_{ii}$  for an arbitrary value of  $Q$  at a specific location in concrete is a difficult task. A simpler approach would be to seek a case that corresponds to a *zero* value of  $t_{ii}$ . This can be accomplished by pre-cracking a drilled hole in the bottom flange in such a manner that the crack would run parallel to the girder span and detect the closing of the crack after a side pressure  $Q$  is applied. The instant of complete crack closure could be viewed as an indication of a zero value for the stress normal to the crack surface at the hole's perimeter.

In summary, the following are the steps in the proposed new technique:

- Drill a hole in the bottom flange of prestressed girder.
- Pre-crack the hole so that the crack would start at coordinates  $(a, 0^\circ, 0)$  and run parallel to the girder pan. It should be noted that the size of this crack is small, approximately 1 inch.
- Increase the side pressure ( $Q$ ) over a limited width ( $W$ ).
- Determine the side pressure ( $Q$ ) at which the crack just completely closes.
- Using an appropriate  $K$  factor obtained from analysis and the side pressure ( $Q$ ) corresponding to the crack closure, an analytical equation will then give  $S$ , the available stress at the extreme fiber of the bottom flange of the prestressed girder.

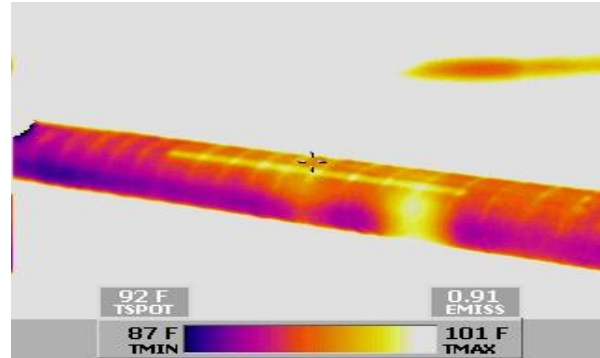
The key to application of this method to measure the available prestress in compressed elements is accurate determination of the  $K$  factor, which is very specific to a given geometry.

## **A.6 Methods to Characterize Duct Location or Condition**

The position of the duct or sheath used in post-tensioned and cable stay systems is important for the performance of those structures. With regard to duct integrity, a solid a durable duct provides a critical layer of protection for the tendon and cable system from the surrounding elements (i.e., protection against corrosion). The need to determine duct position for the case if internal post-tensioned structures arises when construction errors leave in situ position in doubt, or if ducts must be located for direct assessment, for example with a borescope. Thus NDT methods that can reliably characterize duct position and integrity in post-tensioned and cable stay systems are needed.

### A.6.1 Infrared Thermography (IT)

The Infrared Thermography (IT) method has been validated in the laboratory and proven to be economically and technically viable for cable cover pipe defects, as illustrated in Figure A.34. In this method, variations and disruptions to heat flow are used to detect surface defects on the test object.



**Figure A.35: Infrared image of polyethylene cable duct, indicating split at surface**

One promising new technology investigated by the P.I. in collaboration with Drs. Poulain, Alexander, and Krause at the University of Nebraska-Lincoln is a nondestructive active thermal (infrared) sensing system. The system uses an infrared focal plane array camera to measure the radiation intensity of a heated object, in this case being the steel rebar. The method relies on the detection of the variations in the surface temperature profile during transient heat flow. Because various materials in concrete have different thermal conductivity, any pocket or section loss due to corrosion could be detected. Unlike traditional thermal sensing that relies on passive thermal heating by the sun, the proposed method uses electrical current to actively heat the object in question in order to produce large thermal transients that can be easily detected by the infrared camera. Similar methods have been used for locating landmines in soil. Table A-13 summarizes the inherent characteristics and applications of this technique.

**Table A-13: Summary of Inherent Characteristics and Application of Infrared Thermography**

<b>Advantages</b>	<b>Disadvantages</b>	<b>Best application case</b>	<b>Application with regard to duct type</b>
<ul style="list-style-type: none"> <li>• Rapid and convenient contactless technique.</li> </ul>	<ul style="list-style-type: none"> <li>• Cannot provide meaningful information about internal ducts.</li> </ul>	<ul style="list-style-type: none"> <li>• Characterization of exterior duct or tape condition of duct on cable stays.</li> </ul>	<ul style="list-style-type: none"> <li>• Applicable mainly to cable stay ducts.</li> <li>• Likely not applicable to post-tensioned ducts of any sort.</li> </ul>

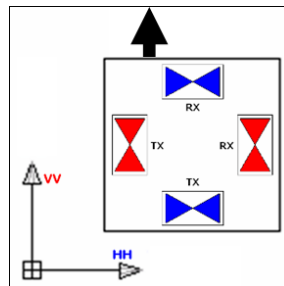
### **A.6.2 Impulse Radar (GPR)**

GPR is used to locate ducts in post-tensioned bridges. However steel ducts completely reflect the radar signal since they are conductive, so that the tendon breaks or grout defects inside the duct cannot be detected. This was also reported by Pollock, et al, 2008 in December, 2008 by David G. Pollock, Kenneth J. Dupuis, Benjamin Lacour, and Karl R. Olsen in a report entitled “Detection of Voids in Prestressed Concrete Bridges Using Thermal Imaging and Ground-Penetrating Radar” from Washington State University, Department of Civil and Environmental Engineering FHWA Project DTFH61-05-C-00008, Task No. 8. The research concluded that infrared thermography could find most of the voids in ducts due to heat differences with active infrared heating for 8 inch thick walls, but not for 12 inch thick walls. They also commented that the GPR has a better prospect of detecting grout vs. void for plastic ducts, but the signals still reflect strongly from the PT tendons.

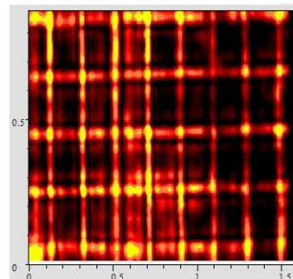
Olson Engineering is now using an innovative GPR system developed by IDS of Pisa, Italy, called the Aladdin system that provides for very precise 3-D tomographic imaging of internal concrete conditions. The Aladdin has 2 pair of antennae, which are referred to as full polar or bipolar, inside at 2 GHz that are at right angles to each other, so one only need to scan in one direction to image the rebars. It also has the option to test with 2 more antenna combinations at a 45 degree angle for angled rebars. The Aladdin system and an example 3-D image are shown in Figure A.35 through Figure A.37.



**Figure A.36: IDS Aladdin radar on test pad**

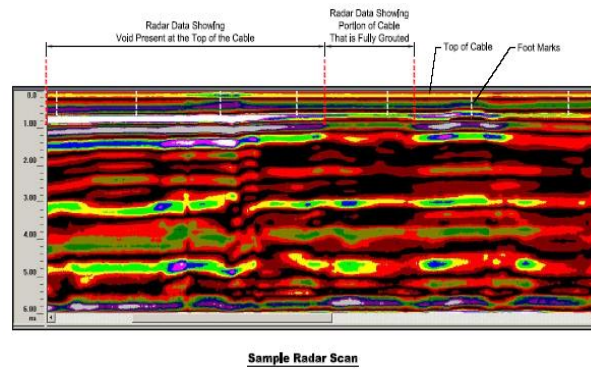


**Figure A.37: Full-polar 2 GHz antenna**



**Figure A.38: 3-D image of rebar at 0.1 m deep**

GPR has the potential to monitor grout condition within nonconducting (plastic) ducts. In particular, GPR is likely sensitive to the occurrence of soft, non-setting and chalky grout or cases of water intrusion since these cases are likely to exhibit higher levels of moisture and electrolytes within the grout, as indicated in Figure A.38.



**Figure A.39: Illustration of GPR B-scan image of grouted plastic duct. an occurrence of improper grouting (voiding) is indicated by high reflection levels.**

Table A-14 summarizes the inherent characteristics and applications of this technique.

**Table A-14: Summary of Inherent Characteristics and Application of Impulse Radar (GPR)**

Advantages	Disadvantages	Best application case	What improvement can be made	Application with regard to duct type
<ul style="list-style-type: none"> <li>Established method.</li> <li>Contactless method and thus can be rapidly applied.</li> <li>Very sensitive to embedded metal.</li> </ul>	<ul style="list-style-type: none"> <li>Disrupted by high levels of embedded metal (shadow zone problem) and cannot be applied to inspect within metal ducts.</li> <li>Affected by electrical properties and not by mechanical properties.</li> </ul>	<ul style="list-style-type: none"> <li>Detecting location of embedded metal ducts and reinforcing bars.</li> </ul>	<ul style="list-style-type: none"> <li>Signal processing can be used to improve performance for voiding in plastic ducts, and perhaps to characterize chemical makeup and moisture within plastic ducts.</li> </ul>	<ul style="list-style-type: none"> <li>Applicable to plastic ducts only for internal inspection, both internal and external.</li> <li>Applicable to metal ducts for location only.</li> </ul>

# **Appendix B: List of Survey Questions and Summary of Findings**



## Questions

- 1- Do you have any bridges with need for corrosion inspection, associate with embedded steel strands or cable stay?

Yes \_\_\_\_ No \_\_\_\_

- a. If yes, please identify the bridge types from the list stated below

<input type="checkbox"/> Box beam bridges	<input type="checkbox"/> Bulb-tee or I-beam bridges
<input type="checkbox"/> Double-stemmed beam bridges	<input type="checkbox"/> Voided slab beam bridges
<input type="checkbox"/> Post tension girder bridges	<input type="checkbox"/> Segmental bridges
<input type="checkbox"/> Cable stayed bridges	<input type="checkbox"/> Suspension bridges
<input type="checkbox"/> Substructure elements	

- 2- Have you had any major corrosion problems and related challenges in relation to the above?

☐ Yes ☐ No

- a. If yes, please briefly state type of problems or challenges

- 3- Have you carried out any research projects to develop methodology or approaches for detection of corrosion of prestressed – post-tensioned strands or stays in bridges?

☐ Yes ☐ No

- a. If yes, please provide a reference or a contact name and phone number for us to contact

- 4- Have you used any non destructive evaluation tools for inspecting prestressed or post-tensioned strands or stays in bridges either during biennial inspections or as part of special inspections?

☐ Yes ☐ No

- a. If yes, please provide a reference or a contact name and phone number for us to contact

- 5- Florida Department of Transportation in association with Florida International University has initiated a research project to develop a roadmap for enhancing corrosion detection. Are you interested to be kept informed of this project, its outcome, tools etc?

☐ Yes ☐ No

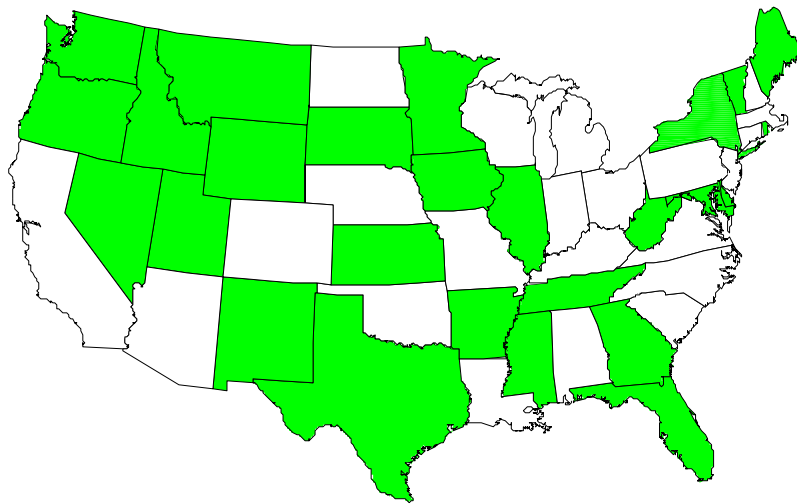
- a. If yes, please provided a name and contact address (email, address and phone number) for us to contact

Please send form back to:

Atorod Azizinamini, Ph.D., P.E.  
Chair and Professor  
Department of Civil and Environmental Engineering  
Florida International University  
10555 W. Flagler Street, EC 3677  
Miami, FL 33174  
Tel: (305) 348-2824  
Fax: (305) 348-2802  
E-Mail: [atorod.azizinamini@fiu.edu](mailto:atorod.azizinamini@fiu.edu)

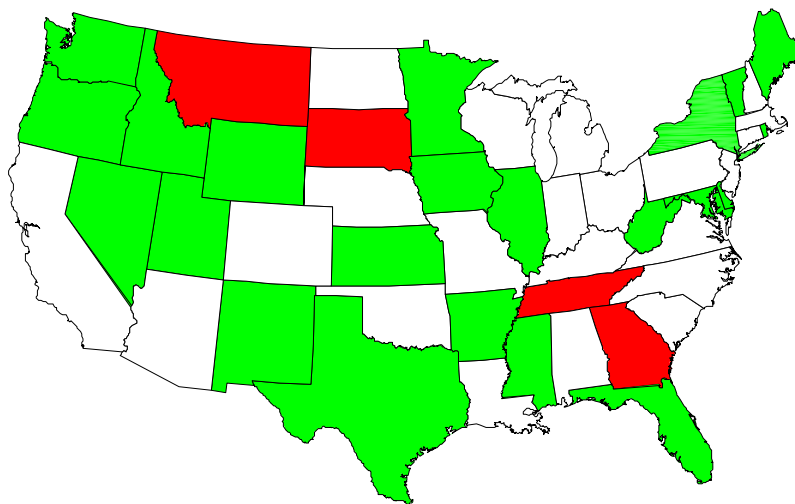
Following are some of the excerpts from the May 2011 survey conducted by FIU.

The map shown in Figure B-1 identifies the 27 states that responded to the survey.



**Figure B.1: Participation in survey (green = participated; white = not participated)**

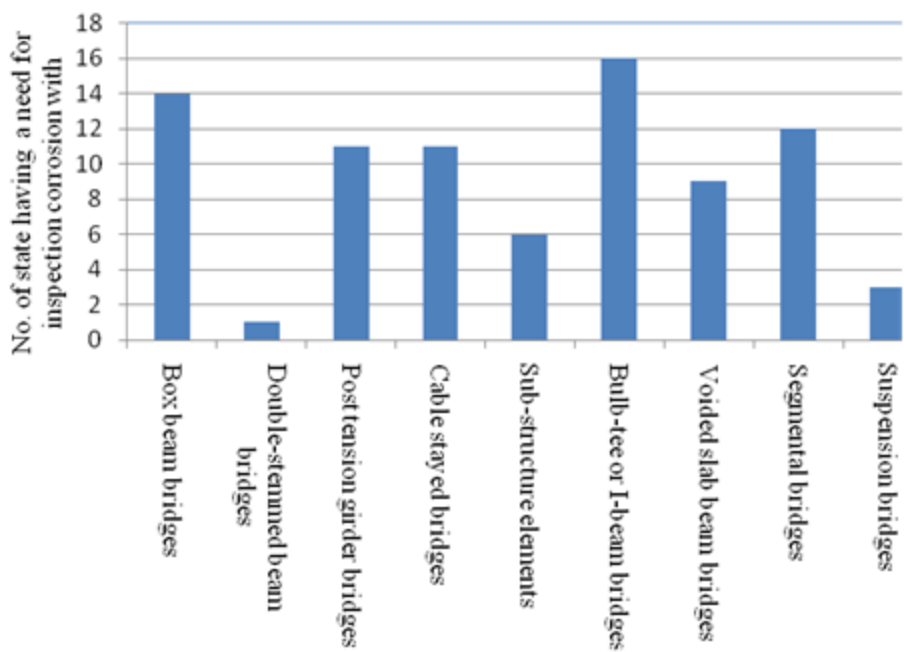
Out of the 27 responding states, 23 states were having bridges with need for corrosion assessment of post-tensioning and stay cables. Figure B-2 shows the states having bridges with need for corrosion inspection, associate with embedded steel strands or cable stay.



**Figure B.2: States having bridges with need for condition assessment (green = yes; red = no; white = not participated)**

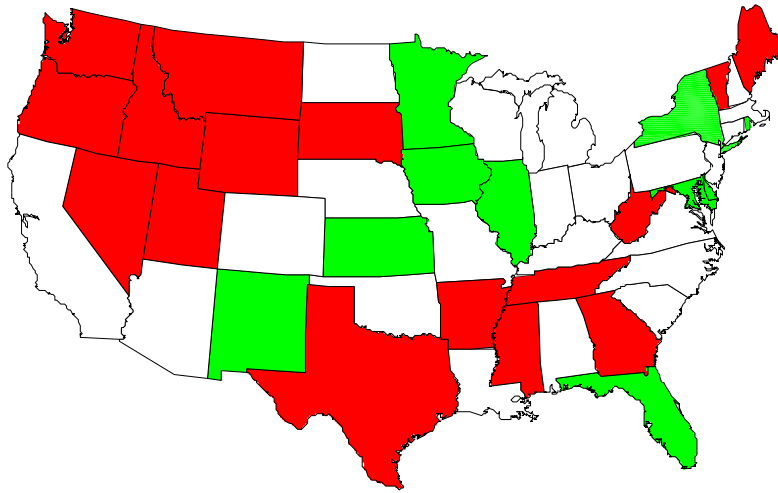
Survey questionnaire also provided information for identifying types of bridges needing condition assessment. Figure B-3 shows the different types of bridges and the number of states that could use NDE

methods for condition assessment. Bulb-tee or I-beam bridges were reported to have a need for corrosion inspection by most of the states.



**Figure B.3: Types of bridges that need corrosion inspection in different states**

Ten of the responding states reported to have major corrosion problems and bridge-related challenges. Figure B-4 shows these states in green. Specific problems identified by each state are summarized in Table B-1.



**Figure B.4: States having major corrosion challenges/problems (green = yes; red = no; white = not participated)**

**Table B-1: Major Corrosion Problems by States**

State	Problem or Challenge
Delaware	“During our biennial inspections of C&D canal (Cable Stayed Bridge) bridge, we found cracks in the High Density Polyethylene (HDPE). There were cracks in the grout inside the HDPEs, which exposed the prestressed tendons”.
Florida	“Corrosion in post-tensioning ducts in segmental bridges and in post-tensioned substructure units”.
Illinois	“Box beam bridges have experienced significant corrosion problems. Other types listed could also benefit from simple, efficient corrosion inspection methods”.
Iowa	“For prestressed concrete beams there is an issue with corrosion at the ends of the beams, especially under expansion joints. For cable-stayed, we have not had any major problems but there is a question if the grout in grouted cables is breaking up and if there is any water getting inside the stay tubes”.
Kansas	“Recently hired consultant to inspect some post-tensioned box girder bridges. A large amount of voids were detected. Need to determine whether filling voids with new grout to old will cause further corrosion problems”.
Maryland	“We have had a number of problems related to original construction defects and also leaking between adjacent box beams. This has resulted in corrosion to the prestressing tendons. The extent of the corrosion has been significant to the point where we have replaced a few structures. A particular challenge has been how to determine the extent of remaining bridge capacity, when deterioration has been detected, without doing full load testing. We have been utilizing guidelines developed by several other states to help with assumptions for load ratings, including Penn DOT 431-07-08 and Illinois DOT “Guidelines for Estimating Strand Loss in Structural Analysis of (Precast Prestressed Concrete) PPC Deck Beam Bridges”. We have also increased our inspection intensity to be more in line with the procedures used in the Michigan Inspectors Handbook from the Wayne University study”.

State	Problem or Challenge
Minnesota	“A City of Minneapolis bridge (post-tensioned concrete box girder constructed in the early 1980s) was recently closed due to advanced corrosion discovered in some of the bottom slab PT tendons. The extent of corrosion was not known until the concrete was removed”.
New Mexico	“For Box Beam bridges with prestressing strands, we have had some corrode to the point of spalling the bottom flange then the strands break. Other states have had this problem as well”
New York	“Estimating the number and extent of deteriorated strands/rebar for load rating/inspection rating purposes as concrete cover precludes exact determination”.
Rhode Island	“Voids in grout tubes trapped moisture and lead to corrosion of strands”

**Appendix C: Brief Summary of Agenda  
and Findings from International  
Workshop Held on October 27 and 28,  
2011, at FIU**



## **International Workshop**

### **Nondestructive Testing Techniques for Detecting Corrosion or Factors Causing Corrosion**

In order to develop a roadmap for enhancing the detection of corrosion in steel strands in existing post-tensioned bridges a workshop was organized at Florida International University, in Miami, Florida. The objective of workshop was to review the latest technologies worldwide in various engineering fields and applicable to bridges and developing a roadmap for future. The workshop was two days long from Thursday October 27 (8:00 a.m. to 5:00 p.m.) to Friday October 28 (8:00 a.m. to noon), 2011. Workshop was attended by experts from several countries.

The main agenda for the workshop was to:

- a) Evaluate the available methodologies for detecting corrosion in post-tensioned bridges
- b) Identify the technologies that are used in other engineering field, with promise for application in bridge engineering, with or without additional research
- c) Develop a consensus for future research direction

Complete agenda of the work shop was as follows

#### **Thursday, October 27**

**FIU, Modesto A. Maidique Campus (MMC), 11200 S.W. 8th Street, Miami, Florida 33199**

#### **College of Business Complex, Room 300 (CBC 300)**

8:00 to 8:10 a.m.	Welcome – Atorod Azizinamini, FIU Richard Kerr, FDOT
8:10 to 9:00 a.m.	History of Corrosion Challenges in Florida
9:00 to 9:45 a.m.	FDOT Corrosion Research- Past to Present
9:45 to 10:00 a.m.	Break

10:00 to 10:30 a.m.	Investigation of External Post-tensioning Tendons on a Segmental Bridge- Jim Jacobsen, FDOT
10:30 – 11:00	ASBI – Corrosion- State of the practice in segmental post-tensioned concrete bridges– Randy Cox
11:00 – 11:30 a.m.	Current FDOT research project- Status and Workshop objectives- Azizinamini, Ph.D.
11:30 – Noon	Various NDT methods identified within current FDOT project – Larry Olson
Noon- 1:00 p.m.	Lunch
1:00 p.m. to 1:30	Radar Imaging- New Approach – Stavros Georgakopoulos, FIU
1:30 p.m. to 2:00	NASA Experience with Corrosion Detection Technologies- Luz Calle
2:00 p.m. to 2:30	Corrosion Detection- Frank Papworth- State of practice in Australia
2:30 p.m. to 3:15	Corrosion Detection- Horst Scheel- State of practice in Germany
3:15 p.m. – 3:30	Break
3:30 p.m. to 4:10	Corrosion Detection- Gnägi, Adrian- State of practice in Switzerland
4:10 p.m. to 4:40	Nondestructive testing methods- John Popovics- University of Illinois- Urbana
4:40 p.m. to 5:00 p.m.	Technologies to identify hidden elements

## Friday Oct 28, 2011

8:00 a.m. to 9:00	<b>Open Discussion- <i>What Should we Consider-</i></b> Developing consensus on elements of effective inspection approaches for corrosion- Objective of this segment of the workshop is to identify the elements of an effective inspection approaches for detecting corrosion. Discussion will concentrate on existing structure. However, steps that could be taken for new structures will also be discussed.
9:00 a.m. to 10:00	<b>Open discussion – <i>What are Out There- Identifying promising technologies within other industry-</i></b> The objective of this segment of the workshop is to brainstorm technologies and approaches used in other industries that as is or with modification could have application for developing an enhanced inspection methodologies
10:00 a.m. to 10:15	Break
10:15 to 11:00	<b>Open Discussion- <i>Let's be Specific-</i></b> Developing consensus on promising technologies that could be utilized, as is, or with modifications, within effective inspection approaches for corrosion. Elements of an effective inspection approaches, will require utilizing nondestructive testing. This segment of the workshop will concentrate on nondestructive techniques that could be utilized within effective inspection strategies, their limitation, additional work that should be conducted to enhance their effectiveness, etc.

11:00 a.m. to Noon	<b>Open Discussion- <i>Let's put it All Together-</i></b> Identifying elements of roadmap for developing effective inspection approaches. This segment of the workshop will concentrate on summarizing the entire outcome of the workshop and developing a roadmap for future.
Noon- 12:30 p.m.	<b>Closing Remark – <i>Lets Continue our Cooperation-</i></b> Summary, Conclusion, Future Get Together and Communication– FIU and FDOT
12:30 p.m.	Meeting adjourn

**Table C-1: Advantages and Disadvantages of some of the NDE Methods discussed during Oct 27 and 28, 2011 International workshop held at FIU and chaired by Atorod Azizinamini (P.I.)**

<b>NDE Method</b>	<b>Advantages</b>	<b>Disadvantages</b>	<b>Application case</b>	<b>What improvement can be made</b>	<b>Application with regard to duct type</b>
Electrochemical tests (half-cell potential, Linear polarization resistance (LPR), Electro-impedance Spectroscopy (EIS))	Potential to measure meaningful data related to active corrosion of strand	Electrical connection to tendon required; sensors must be placed within the duct to monitor tendon. Difficult to apply to existing post-tensioned (PT) ducts with current available technology, because of the requirement that sensors must be inside the duct.	Best application: standard steel reinforcing bar and tendon systems in concrete not within ducts.	Develop robust sensors and sensing systems that are applicable within ducts.	Probably not applicable to either internal or internal ducts at this time
Impulse response	Potential to measure mechanical compliance of a duct system, which could reflect a duct grouting or other problem.	Probably not sensitive to small defects	Best application: external ducts, looking for large void in grout		Probably applicable only to external ducts, giving one global value for entire duct. Unlikely to work for internal ducts unless void is very large.
Acoustic sounding (hammer tap)	Practical and relatively easy; fairly accurate for detecting “dry” voids in the grout	Not sensitive to “soft” or unset grout. Subjective test that is operator dependent.	Best application: external plastic duct looking for dry voiding in grout	Automate process and quantify results with acoustic sensors and appropriate data analysis	Applicable to external ducts only.
Magnetic flux leakage (MFL)	Can indicate local wire breaks (or member thinning) in near-surface tendons; Established test method; a contactless test that does not require connection to tendon; works for both metal and plastic ducts	Some expertise may be needed to interpret signals. May need many magnetizing pre-sessions before signals are reliable. Cannot detect break in underlying tendons, or in anchorage region	Best application: identifying wire breaks in external, plastic ducts.	Improved performance for congested steel sections and within anchorage region	Applicable to both internal and external ducts

<b>NDE Method</b>	<b>Advantages</b>	<b>Disadvantages</b>	<b>Application case</b>	<b>What improvement can be made</b>	<b>Application with regard to duct type</b>
Impact echo	Can identify duct voids as an apparent reduction in thickness resonant frequency; established test; reported to be fairly sensitive	Signals may be difficult to interpret, some expertise needed; conventional tests (contact) can be slow; difficult to apply in anchorage region or for complicated element geometries; may be less sensitive to voiding in plastic ducts	Best application: detection of voids in internal metal ducts	Method can be improved with graphical image for data presentation	Applicable to internal ducts.
Ultrasonic s-wave imaging	Can be used to identify internal reflectors within concrete, including ducts; graphical output is easy to interpret; may be applicable to anchorage region	May be difficult to distinguish voided from filled ducts with commercially available equipment;	Best application: location of internal ducts, both plastic and metal.	Improve data analysis and data presentation to better identify voided ducts (e.g., using phase information)	Applicable to internal ducts, both metal and plastic
Radiography	Can identify wire breaks and grout voiding; graphical output that is easy to interpret; may be applicable to anchorage region	Significant safety and cost concerns; test geometry and access may be limited; radiograph gives no depth of field information	Very broad application	Can be improved by presenting data in 3-D visual format, instead of single radiograph	Applicable to both internal and external ducts
Pulsed Radar (GPR)	Established method; contactless method and thus can be rapidly applied; very sensitive to embedded metal.	Disrupted by high levels of embedded metal (shadow zone problem) and cannot be applied to inspect within metal ducts; affected by electrical properties, not mechanical properties	Best application: detecting location of embedded metal ducts and reinforcing bars	Signal processing can be used to improve performance for voiding in plastic ducts, and perhaps to characterize chemical makeup and moisture within plastic ducts.	Applicable to plastic ducts only for internal inspection, both internal and external. Applicable to metal ducts for location only.

<b>NDE Method</b>	<b>Advantages</b>	<b>Disadvantages</b>	<b>Application case</b>	<b>What improvement can be made</b>	<b>Application with regard to duct type</b>
Acoustic emission	Can indicate occurrence of a wire break, and in some cases may indicate approximate location; established technology	Expensive; process generates large volumes of data that can be difficult to manage and interpret; individual signal may be difficult to interpret, and some expertise needed	Best application: locating breaks in external ducts (either plastic or metal).		Possibly applied to both internal and external ducts, both metal and plastic ducts
Smart coating technology for indication, mitigation or self-healing of corrosion	Exciting potential to mitigate or indicate corrosion	Still not developed for civil engineering application, and especially not to concrete PT systems			Not yet ready to be applied to PT duct systems
Nuclear density gauge	Possibly use to monitor internal density changes within ducts				Probably practical for looking for voids in both plastic and metal external ducts
Internal sensors within duct (time-domain reflectometer (TDR), fiber optic, environmental sensors)	Exciting potential; may be able to monitor corrosive environment and/or fiber breaks within the duct.	Application to duct is likely problematic in terms of survivability; would be applicable to new ducts only.			Not viable at the present time.
Ultrasonic guided wave propagation within tendon.	Exciting potential to monitor tendon condition near ends and anchorage zones	Ends of tendons must be exposed and accessible; complicated technology that is difficult to apply and interpret.	Technology is not yet viable for application to embedded tendons in concrete		